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CFHTLenS: co-evolution of galaxies and their dark matter haloes

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ABSTRACT

Galaxy–galaxy weak lensing is a direct probe of the mean matter distribution around galaxies. The depth and sky coverage of the Canada–France–Hawaii Telescope Legacy Survey yield statistically significant galaxy halo mass measurements over a much wider range of stellar masses ($10^{8.75}$ to $10^{11.3} M_{\odot}$) and redshifts ($0.2 < z < 0.8$) than previous weak lensing studies. At redshift $z \sim 0.5$, the stellar-to-halo mass ratio (SHMR) reaches a maximum of 4.0 ± 0.2 per cent as a function of halo mass at $\sim 10^{12.25} M_{\odot}$. We find, for the first time from weak lensing alone, evidence for significant evolution in the SHMR: the peak ratio falls as a function of cosmic time from 4.5 ± 0.3 per cent at $z \sim 0.7$ to 3.4 ± 0.2 per cent at $z \sim 0.3$, and shifts to lower stellar mass haloes. These evolutionary trends are dominated by red galaxies, and are consistent with a model in which the stellar mass above which star formation is quenched ‘downsizes’ with cosmic time. In contrast, the SHMR of blue, star-forming galaxies is well fitted by a power law that does not evolve with time. This suggests that blue galaxies form stars at a rate that is balanced with their dark matter accretion in such a way that they evolve along the SHMR locus. The redshift dependence of the SHMR can be used to constrain the evolution of the galaxy population over cosmic time.

Key words: gravitational lensing: weak – galaxies: haloes – cosmology: observations – dark matter.

1 INTRODUCTION

A full understanding of the co-evolution of the stellar, gaseous and dark matter (DM) components of galaxies, and the physical causes thereof, is the primary goal of studies of galaxy formation and evo-

lution. Observations directly yield a snapshot of the luminosities (and stellar masses) of the galaxy population at a given redshift, whereas numerical studies most easily predict the abundance and evolution of DM haloes. One way to connect these two is with the ‘abundance matching’ ansatz: galaxies are assigned to DM haloes by rank-ordering each set and matching them one-to-one from highest to lowest. Using this assumption, Marinoni & Hudson (2002)

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showed that galaxy formation is most efficient in haloes of mass $\sim 10^{12.5} M_{\odot}$, at which mass 25 per cent of the baryons had been converted to stars. The method of Marinoni & Hudson (2002) was based on the summed luminosity of all galaxies in a halo, and was then extended to consider central galaxies and satellites (Yang, Mo & van den Bosch 2003; Vale & Ostriker 2004; Conroy, Wechsler & Kravtsov 2006; Moster et al. 2010). Another approach is to populate haloes with galaxies (the so-called halo occupation distribution, or HOD) in order to reproduce galaxy clustering (Jing, Mo & Boerner 1998; Peacock & Smith 2000; Seljak 2000; Berlind & Weinberg 2002; Cooray & Sheth 2002; Kravtsov et al. 2004; Zehavi et al. 2005; Coupon et al. 2012). While these methods are powerful, they are model-dependent in the sense that some critical assumptions are made in the statistical link between galaxies and their haloes.

Connecting the galaxies to their DM haloes in a more direct fashion requires probes of the gravitational effects of the DM haloes. There are several ways to measure galaxy masses at intermediate redshifts. Traditionally, dynamical methods have been used to obtain masses. All dynamical methods make some assumption regarding the dynamical equilibrium of the system. Furthermore, some methods, such as the Tully–Fisher (Tully & Fisher 1977) relation or the Fundamental Plane (Djorgovski & Davis 1987) only probe the inner regions of the halo. Other methods, such as satellite kinematics (e.g. More et al. 2011), reach further out in the halo but are difficult to apply at intermediate redshifts due to the faintness of the satellites.

A powerful alternative approach to these dynamical methods is to use weak gravitational lensing to measure the masses of galaxy DM haloes (Brainerd, Blandford & Smail 1996). Weak lensing is sensitive to all of the matter that surrounds the galaxy and along the line of sight. Because galaxy–galaxy lensing (GGL) is an ensemble mean measurement, this includes matter that is statistically correlated with galaxy haloes: in other words, GGL is measuring the galaxy–matter cross-correlation function. This has led to the development of a ‘halo model’ (e.g. Mandelbaum et al. 2006, hereafter M06) to interpret the GGL measurements in a similar way as had been done in studies of galaxy clustering. The halo model has been applied to recent weak lensing data sets from the RCS2 by van Uitert et al. (2011), and the Canada–France–Hawaii Telescope (CFHT) Lensing Survey (CFHTLenS) by Velandier et al. (2014, hereafter V14).

The focus of this paper is to use GGL to study galaxy evolution, or more specifically, the evolution with redshift of the stellar-to-halo mass ratio (hereafter SHMR). In this sense, this paper parallels recent efforts to extend the abundance matching and HOD methods to higher redshifts. The promise of using GGL to probe galaxy evolution goes back to Hudson et al. (1998), who found no relative evolution between the GGL signal in the *Hubble Deep Field* and the low-redshift Tully–Fisher and Faber–Jackson relations. Leauthaud et al. (2012, hereafter L12) performed a combined HOD analysis using GGL, abundance matching and correlation functions on Cosmic Evolution Survey (COSMOS) data. They found that the peak value of the SHMR did not evolve with redshift, but that SHMR ‘downsized’ in the sense that the halo (and stellar) mass at which it peaks decreases with cosmic time. The RCS2 GGL study of van Uitert et al. (2011) examined the evolution of the SHMR but lacked the statistical power to place strong constraints. V14 analysed GGL in the CFHTLenS, but limited to the redshift range $0.2 < z < 0.4$. The combination of depth and area of the CFHTLenS sample allows us, for the first time, to split lens samples by redshift, colour and stellar mass, and hence to measure the evolution of the SHMR using only GGL.

The outline of this paper is as follows. We discuss the CFHTLenS shape and photometric redshift (hereafter photo- z) data in Section 2, and describe the halo model in Section 3. In Section 4, we show the fits of the halo model to the weak lensing data. The SHMR is discussed in Section 5, and the GGL results are compared with SHMR results from other methods. In Section 6, we discuss the interpretation of the SHMR in terms of models of star formation and quenching. We also compare our results for faint blue galaxies to determinations from galaxy rotation curves. Our conclusions are summarized in Section 7.

Throughout, we adopt a ‘737’ Λ cold dark matter (Λ CDM) cosmology: a Hubble parameter, $h \equiv H_0/(100 \text{ km s}^{-1} \text{ Mpc}^{-1}) = 0.7$, a matter density parameter $\Omega_{m,0} = 0.3$ and a cosmological constant $\Omega_{\Lambda,0} = 0.7$. The values of $\Omega_{m,0}$ and $\Omega_{\Lambda,0}$ are consistent with the current best-fitting *WMAP9* cosmology. (Hinshaw et al. 2013, including baryonic acoustic oscillations (BAO) and H_0) as well as with the first *Planck* results (Planck Collaboration XVI 2014, including BAO). There is a well-known tension between the Planck value of h and that derived by Riess et al. (2011), the value adopted here lies in between these. All masses, distances and other derived quantities are calculated using this value of h .

2 DATA

The data used in this paper are based on the ‘Wide Synoptic’ and ‘Pre-Survey’ components of the Canada–France–Hawaii Telescope Legacy Survey (CFHTLS), a joint project between Canada and France. The CFHTLenS collaboration analysed these data and produced catalogues of photometry, photometric redshifts and galaxy shapes as described below.

2.1 Images and photometry

The survey area was imaged using the Megaprime wide field imager mounted at the prime focus of the CFHT. The MegaCam camera is an array of 9×4 CCDs with a field of view of 1 deg^2 . The CFHTLS wide synoptic survey covers an effective area of 154 deg^2 in five bands: u^* , g' , r' , i' and z' . This area consists of four independent fields, W1–4 with a full multicolour depth of $i'_{AB} = 24.7$ (for a source in the CFHTLenS catalogue). The images have been independently reduced within the CFHTLenS collaboration; the details of the data reduction are described in detail in Erben et al. (2013).

2.2 Source shapes

CFHTLenS has measured shapes for 8.7×10^6 galaxies (Heymans et al. 2012; Miller et al. 2013) with $i'_{AB} < 24.7$ with the *lensfit* algorithm (Miller et al. 2007; Kitching et al. 2008; Miller et al. 2013). These have been thoroughly tested for systematics within the CFHTLenS collaboration (see Heymans et al. 2012). The ellipticities have a Gaussian scatter of $\sigma_e = 0.28$ (Heymans et al. 2013). The ellipticities are almost unbiased estimates of the gravitational shear: there is a small multiplicative correction discussed in Section 2.5 below. We do not apply the weak additive c -term correction discussed in Heymans et al. (2012) as we found that it had no effect on our GGL results (V14).

2.3 Photometric redshifts and stellar masses

The CFHTLenS photometric redshifts, z_p , are described in detail in Hildebrandt et al. (2012). Over the redshift range of interest for this paper, these photo- z 's are typically precise to $\pm 0.04(1 + z)$,

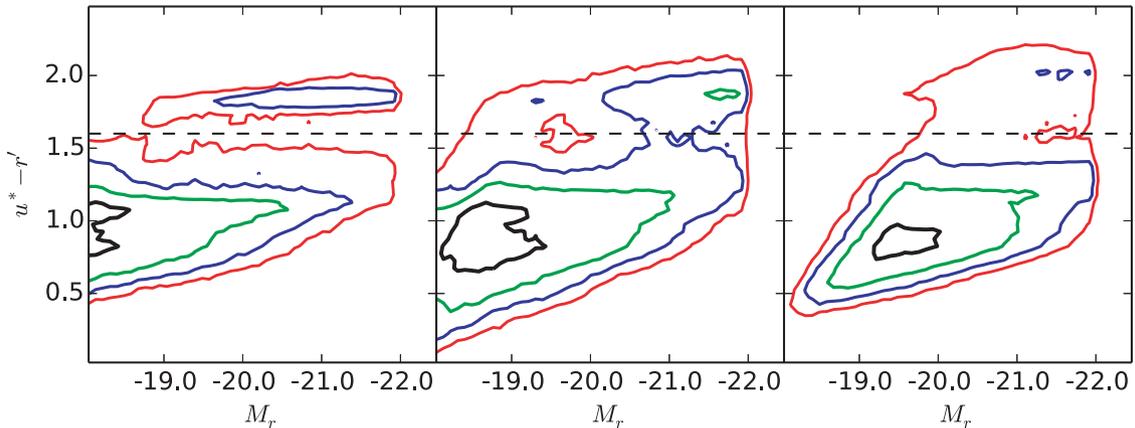


Figure 1. Colour–magnitude diagrams for CFHTLenS galaxies for three redshift bins $0.2 \leq z_p < 0.4$, $0.4 \leq z_p < 0.6$, $0.6 \leq z_p < 0.8$ from left to right. The contours show density of galaxies in colour–magnitude space relative to the peak density in that redshift bin. The colour is rest-frame $u_{\text{CFHT}}^* - r'_{\text{CFHT}}$, the horizontal dashed line shows the colour 1.6 used to separate red and blue populations.

with a 2–5 per cent catastrophic failure rate. The photo- z code also fits a spectral template, ranging from $T = 1$ (elliptical) to $T = 6$ (starburst). Here, we correct the photometric redshifts for small biases with respect to spectroscopic redshifts, as discussed in more detail in Appendix A.

Stellar masses, M_* , are measured using the LEPHARE (Ilbert et al. 2006) code, with the photometric redshift fixed at the value found by Hildebrandt et al. (2012). The $u^*g'r'i'z'$ magnitudes are fit using Bruzual & Charlot (2003) models with varying exponential star formation histories and dust extinction, as described in more detail in V14. That paper also compared the stellar masses from CFHTLenS $u^*g'r'i'z'$ photometry to those determined using the same code but with $u^*g'r'i'z'$ plus infrared photometry (based on WIRCam Deep Survey (WIRDS) data). There are slight systematic differences between WIRDS and CFHTLenS stellar masses (for both red and blue galaxies) amounting to 0.1–0.2 dex. The LEPHARE fits also produce absolute magnitudes in all Megaprime bands. We will use the rest-frame $u^* - r'$ colours to separate red and blue galaxies in Section 2.4.1 below.

2.4 Sample selection

2.4.1 Lenses

We select lenses in the range $0.2 < z_p < 0.8$ with $i'_{\text{AB}} < 23$. We use the Megaprime rest-frame $u^* - r'$ colours to separate red and blue galaxies, with the division at $u^* - r' = 1.60$, independent of magnitude or redshift, as we observe no strong evolution in the red/blue division. The colour–magnitude diagram for lenses in three different redshift bins is shown in Fig. 1. This criterion is similar to, but not identical to that of V14, who used the fitted spectral template type T to separate the red and blue populations. In this paper, we choose to use colour to make subsequent comparisons with our results more straightforward. This corresponds approximately to $u'_{\text{SDSS}} - r'_{\text{SDSS}} = 1.87$, similar to the colour $u'_{\text{SDSS}} - r'_{\text{SDSS}} = 1.82$ used by Baldry et al. (2004) to separate red and blue galaxies at faint luminosities in the Sloan Digital Sky Survey (SDSS).

In addition to the red/blue colour separation discussed above, we will bin lenses by redshift ($0.2 \leq z_p < 0.4$, $0.4 \leq z_p < 0.6$, $0.6 \leq z_p < 0.8$). With these cuts, there are 1.62×10^6 blue galaxies and 4.50×10^5 red galaxies, for a total of 2.06×10^6 lenses. We will also bin lenses by r' -band luminosity/stellar mass. However, the stellar masses of individual galaxies are noisy. Were we to bin by

stellar mass, the noise would introduce Eddington-like biases, and this would require simulations to correct (as in e.g. V14). Instead, we bin by r' -band luminosity and use the mean stellar-mass-to-light ratio for that bin to calculate the mean stellar mass of the bin. The r' -band magnitude limits for the bins are chosen for red and blue galaxies separately so that the stellar mass bins are approximately 0.5 dex in width, for $M_* > 10^{8.5} M_\odot$.

2.4.2 Sources

Sources are limited to $i'_{\text{AB}} < 24.7$ from unmasked regions of the CFHTLS. We use the full unmasked survey area, including the fields which did not pass cosmic shear systematics tests described in Heymans et al. (2012). V14 found that, for GGL, there was no difference between results from these fields and the remainder of the survey. We also limit the source redshifts to $z_p < 1.3$, where the photo- z s are reliable (Hildebrandt et al. 2012). Excluding masked areas, there are 5.6×10^6 sources, corresponding to an effective source density of 10.6 arcmin^{-2} (Heymans et al. 2012).

2.4.3 Lens–source pairs

From the lens and source samples, we analyse all lens–source pairs with $\Delta z_p > 0.1$. At the median redshift of the lenses $z_1 \sim 0.5$, the typical error in source redshift is ~ 0.05 , hence this yields a $\sim 2\sigma$ separation in redshift space. Note that later we will downweight close lens–source pairs, with the result that any physical pairs in which one member is scattered up by photo- z errors will have low weight in any case.

We also only consider lens–source pairs that are not too close on the sky. There are two reasons for this. First, the shapes of background sources may be affected by the extended surface brightness (SB) profile of bright foreground galaxies (Hudson et al. 1998; Velander, Kuijken & Schrabback 2011). Schrabback et al. (in preparation) have examined this issue via simulated galaxy catalogues including realistic SB distributions. They find no additive bias for pairs as close as 3 arcsec. This angular separation corresponds to 10 kpc at $z = 0.2$ or 22.5 kpc at $z = 0.8$. Secondly, it is possible that features within a galaxy (e.g. spiral arms) may be split by the SExtractor (Bertin & Arnouts 1996) software and treated as independent ‘sources’. These fragments will have assigned photo- z s, and our cut $\Delta z_p > 0.1$ should remove most of these spurious pairs.

There remains, however, the possibility of residual contamination, and so a cut based on the luminosity profiles of bright discs is also applied. van der Kruit & Freeman (2011) find that spiral galaxy discs typically truncate at an isophote corresponding to a B -band SB of 26 mag arcsec⁻². The largest discs have low SB; Allen et al. (2006) find few discs with SB (measured at the effective radius) fainter than 24 in B . To be conservative, we use an SB limit of 27 for the isophotal truncation and faint limit of 25 in B for the lowest SB galaxies. This yields an estimated truncation radius of $R_{\text{trunc}} = 37$ kpc for a B -band fiducial magnitude of -20.5 (or an r' -band magnitude of -21.36), and a scaling $R_{\text{trunc}} \propto (L/L_{\text{fid}})^{0.5}$. We adopt double this for the minimum radius, R_{min} , for lens–source pairs around blue galaxies, but with a hard lower limit of 20 kpc and a hard upper limit of 50 kpc. For red galaxies, we adopt the same minimum radius as for blue galaxies. In practice, then this is always larger than the 3 arcsec angular cut discussed above. For each bin of redshift and luminosity, we adopt the larger of the two radii as the minimum projected radius of the lens–source pairs.

2.5 Stacking and weights

The excess surface density,

$$\Delta\Sigma(R) = \overline{\Sigma(<R)} - \overline{\Sigma(R)}, \quad (1)$$

defined as the difference between $\overline{\Sigma(<R)}$, the mean projected surface mass density enclosed within a circle of radius R and $\overline{\Sigma(R)}$, the average surface density at radius R , can be related to the observed tangential shear γ_t via (Miralda-Escude 1991; Fahlman et al. 1994):

$$\Delta\Sigma(R) = \Sigma_{\text{crit}} \langle \gamma_t(R) \rangle, \quad (2)$$

where critical surface density, Σ_{crit} , is given by

$$\Sigma_{\text{crit}} = \frac{c^2}{4\pi G} \frac{D_s}{D_l D_{ls}}, \quad (3)$$

and where D_l is the angular diameter distance to the lens, D_s is the angular diameter distance to the source and D_{ls} is the angular diameter distance between lens and source.

It is necessary to stack a large number of lenses to obtain a statistically significant signal. We calculate the surface mass density as a function of projected separation, R , by summing the tangential component of the source ellipticities over all lens–source pairs. We weight the sources by their *lensfit* weights, w , which includes both the ellipticity measurement error and the intrinsic shape noise (Miller et al. 2013, equation 8). We also weight pairs by $W = \Sigma_{\text{crit}}^{-2}$. The excess surface density is then given by

$$\langle \Delta\Sigma(R) \rangle = \frac{\sum w_j e_{t,j} \Sigma_{\text{crit},ij} W_{ij}}{\sum w_j W_{ij}}, \quad (4)$$

where the sum is over all pairs of lenses, i , and sources, j , in a given R bin, and $e_{t,j}$ is the tangential ellipticity of the source. As in V14, we correct the ellipticities for a small bias in the *lensfit* method: a calibration factor $m(v_{\text{SN}}, r_{\text{gal}})$, which is modelled as a function of the signal-to-noise ratio, v_{SN} , and size of the source galaxy, r_{gal} as described in Miller et al. (2013). Rather than dividing each galaxy shear by a factor $(1 + m)$, which would lead to a biased calibration as discussed in Miller et al. (2013), we apply it to our average shear measurement as a function of lens redshift using the correction

$$1 + K(z_{\text{lens}}) = \frac{\sum w_j W_j [1 + m(v_{\text{SN},j}, r_{\text{gal},j})]}{\sum w_j W_j}. \quad (5)$$

The lensing signal is then calibrated as follows:

$$\langle \Delta\Sigma^{\text{cal}} \rangle = \frac{\langle \Delta\Sigma \rangle}{1 + K(z_{\text{lens}})}. \quad (6)$$

The effect of this correction term on our GGL analysis is to increase the average lensing signal amplitude by 6.5 per cent at $z_{\text{lens}} = 0.2$. As the lens redshift increases, the sources behind it become fainter and smaller and so the correction rises to 9 per cent at $z_{\text{lens}} = 0.8$.

The scatter in the photo- z s of lenses and sources will also introduce a bias in quantities such as the redshift and luminosity of the lens and the distance ratio D_{ls}/D_s . Appendix B discusses how we use simulations of mock catalogues to estimate these biases. These bias estimates are then used to correct all affected quantities.

3 MODELS

3.1 Halo model

We will fit the data with simple halo models that describe the average distribution of total matter around a given galaxy, i.e. the matter–galaxy cross-correlation $\Delta\Sigma(R)$. This can be broken into several terms: the first arises from the galaxy’s own stellar mass and halo, or subhalo if it is a satellite. The second term is the ‘offset-group halo’ term and is the mean distribution of DM around a given satellite galaxy due to the host halo that the satellite inhabits.¹ The third term, which we neglect here because it is important only on very large ($\gtrsim 1000$ kpc) scales, is the two-halo term, which represents the matter in separate haloes that are correlated with the host halo. This yields:

$$\Delta\Sigma(R) = \Delta\Sigma_{\text{1h}}(R) + \Delta\Sigma_{\text{OG}}(R). \quad (7)$$

We now describe each term in more detail.

3.1.1 One-halo term

The so-called one-halo term arises from matter within the galaxy’s own halo: its stars, M_* , and its DM halo. The stellar mass is modelled as a point source:

$$\Delta\Sigma_*(R) = M_*/(\pi R^2). \quad (8)$$

The DM is modelled as a Navarro, Frenk & White (1997, hereafter **NFW**) density profile, parametrized by a virial mass, M_{200} , defined within the radius r_{200} enclosing a mean density 200 times the critical density and a concentration $c_{200} = r_{200}/r_s$ with r_s being the **NFW** scale radius. The concentration of the DM halo, c_{200} , is not free, but instead is fixed as a function of M_{200} and redshift z using the relation given by Muñoz-Cuartas et al. (2011), converted from $(M_{\text{vir}}, c_{\text{vir}})$ to (M_{200}, c_{200}) using the method of Hu & Kravtsov (2003). The excess surface density $\Delta\Sigma_{\text{NFW}}$ for an **NFW** profile is given in Baltz, Marshall & Oguri (2009).

While the **NFW** profile has been shown to be a good description of isolated haloes, the DM haloes of satellite galaxies are expected to be tidally stripped by their ‘host’ DM halo (Taylor & Babul 2001). This effect has been observed in clusters of galaxies by weak lensing (Natarajan, Kneib & Smail 2002; Limousin et al. 2007). Weak lensing has also been used to detect this effect statistically within groups and clusters in the CFHTLenS sample itself by Gillis et al. (2013).

¹ The offset-group term is referred to as the ‘satellite one-halo’ term by M06 and others, but we find that this can be confused with the subhalo’s one-halo term.

They found that, on average, satellites in high-density environments had 35 ± 12 per cent of their mass stripped, or, equivalently, were stripped to a truncation radius of $(0.26 \pm 0.14) \times r_{200}$. Here, we adopt a truncation radius $R_t = 0.4 r_{200}$, which is consistent with the Gillis et al. (2013) result, but which allows a straightforward comparison with the results of previous authors (M06,V14). For this truncated NFW profile (tNFW), we assume $\Delta\Sigma(R) \propto R^{-2}$ beyond the truncation radius:

$$\Delta\Sigma_{\text{tNFW}}(R) = \begin{cases} \Delta\Sigma_{\text{NFW}}(R), & R \leq R_t \\ \Delta\Sigma_{\text{NFW}}(R_t) \times \left(\frac{R_t}{R}\right)^2, & R > R_t \end{cases} \quad (9)$$

The effect of this assumption is examined in greater detail in Appendix D.

In each galaxy subsample as binned by mass, colour and redshift, a fraction, f_{sat} , of the galaxies will be satellites with the remainder being ‘central’ galaxies. Thus, the one-halo term consists of the stellar mass, plus a mean (weighted by satellite fraction) of the central and stripped satellite dark haloes. Note that because of the stripping prescription, for satellites, the fitted value of the parameter M_{200} is the mass before they fell into their host halo. In summary,

$$\Delta\Sigma_{1\text{h}} = \Delta\Sigma_* + (1 - f_{\text{sat}})\Delta\Sigma_{\text{NFW}}(M_{200}, c) + f_{\text{sat}}\Delta\Sigma_{\text{tNFW}}(M_{200}, c). \quad (10)$$

The total one-halo mass, M_{h} is the sum of the baryons and the NFW M_{200} .

3.1.2 Offset-group halo

On intermediate scales (200–1000 kpc), the ‘offset-group halo’ term dominates the $\Delta\Sigma$ signal. This term is given by equations 11–13 of Gillis et al. (2013). In brief, this arises for satellite galaxies only and is due to the DM in their host halo. It is a convolution of the projected NFW profile with the distribution of satellites, and so it depends on the mass of the host group, the concentration, c , of the DM in that group halo and, because it is a convolution of satellite positions, it also depends on the radial distribution of the satellites with respect to group centre. As with the one-halo term, we assume that the hosting DM haloes have concentrations given by the prescription of Muñoz-Cuartas et al. (2011). The distribution of satellite host halo masses is taken from the halo model of Coupon et al. (2012). Finally, we assume that the concentration of satellites, c_{sat} , is the same as that of the DM, which is consistent with the assumptions made by V14 and Coupon et al. (2012). The satellite fraction, f_{sat} is constrained by the offset-group term.

3.2 Fitting the halo model

In addition to the predicted $\Delta\Sigma(R)$, a full treatment of the halo model also contains a detailed prescription of how galaxies occupy haloes as a function of their magnitude and as a function of the halo mass. V14 adopt a halo model in which the parameters of the offset-group term are coupled to the one-halo term. The approach taken here is somewhat different: for satellites, we will adopt the HOD parameters from Coupon et al. (2012). This then specifies the distribution of host halo masses for a given satellite stellar mass and hence the *shape* of the offset-group term. The model for the one-halo term is thus independent of that of the offset-group term. This leaves only two free parameters: M_{200} of the one-halo term; and the satellite fraction, f_{sat} .

In practice, there is some degeneracy between the satellite fraction and the one-halo mass. Coupon et al. (2012) show that there is little evolution in the satellite fraction in their HOD fits and that it is consistent with a linear function in magnitude (or, equivalently, log stellar mass). We adopt these constraints, and fit a non-evolving linear satellite fraction.

4 RESULTS

Figs 2 and 3 show $\Delta\Sigma$ as a function of projected radius for red and blue lens galaxies, respectively. The curves show the fits to the radii between R_{min} and 1000 kpc, based on the point mass plus NFW plus offset-group halo terms. Each panel shows a bin in redshift (increasing from bottom to top) and stellar mass (increasing left to right). Results of the fits are also tabulated in Tables 1 and 2, for red and blue galaxies, respectively. The fitted models are consistent with the data in all cases.

Fig. 4 shows the fitted halo mass as a function of stellar mass M_* for both red and blue galaxies at the three redshifts. Blue galaxies dominate at low mass whereas red galaxies dominate at high masses. Fig. 4 shows that while the halo-to-stellar mass relation of blue galaxies does not evolve as a function of redshift (within the uncertainties), that of red galaxies does.

The slight inflection near $M_* \sim 10^{10.5} M_{\odot}$ indicates that the relationship between stellar mass and halo mass is non-linear, and indeed not well described by a single power law. However, the deviations from linearity are weak. Because of this, and to better appreciate the data and their uncertainties, it is more sensible to plot the SHMR $f_* \equiv M_*/M_{\text{h}}$ as a function of stellar mass.

4.1 Systematics of the fit

In the process of fitting the halo model, we have made several choices. It is worthwhile exploring what effect these choices have on our halo model parameters, in particular on M_{h} and hence f_* . These are (1) neglect of the two-halo term; (2) choice of the $c_{200}(M_{200})$ relation; and (3) constraining the satellite fraction to be non-evolving with a linear slope as a function of stellar mass. We discuss each of these in more detail below.

We argued that the two-halo term is small on the scales that we are fitting ($R < 1000$ kpc). The two-halo term was calculated by V14 for the $z \sim 0.3$ redshift bin. It is a function of scale that peaks between 1000 and 2000 kpc with a peak value $\Delta\Sigma \sim 1\text{--}2 M_{\odot} \text{pc}^{-2}$, depending on the stellar mass and colour bin. This is a factor 5–10 lower than the peak of the offset-group term for red galaxies. It is perhaps only a factor of 2 lower than the offset-group term for blue galaxies. We have repeated our fits after having subtracted off the two-halo term estimated from V14. We find that the satellite fractions are affected by this change: they become lower by an amount which varies from bin to bin but is at most 0.2. The halo masses, M_{h} are hardly affected, however, because while offset-group term and the two-halo term compete on somewhat larger scales, and hence are partially degenerate, the halo mass is dominated by the signal on smaller scales ($R \lesssim 200$ kpc). Fig. 5 shows the effect on the halo masses of including a two-halo term. The effect is very small compared to the random uncertainties.

The concentration–mass relation affects the fits at some level. We have adopted the relation from Muñoz-Cuartas et al. (2011) for relaxed haloes. In contrast, V14 used the concentration–mass relation for all (relaxed and unrelaxed) haloes from Duffy et al. (2008). This makes a small difference to the fitted masses, as shown in Fig. 5.

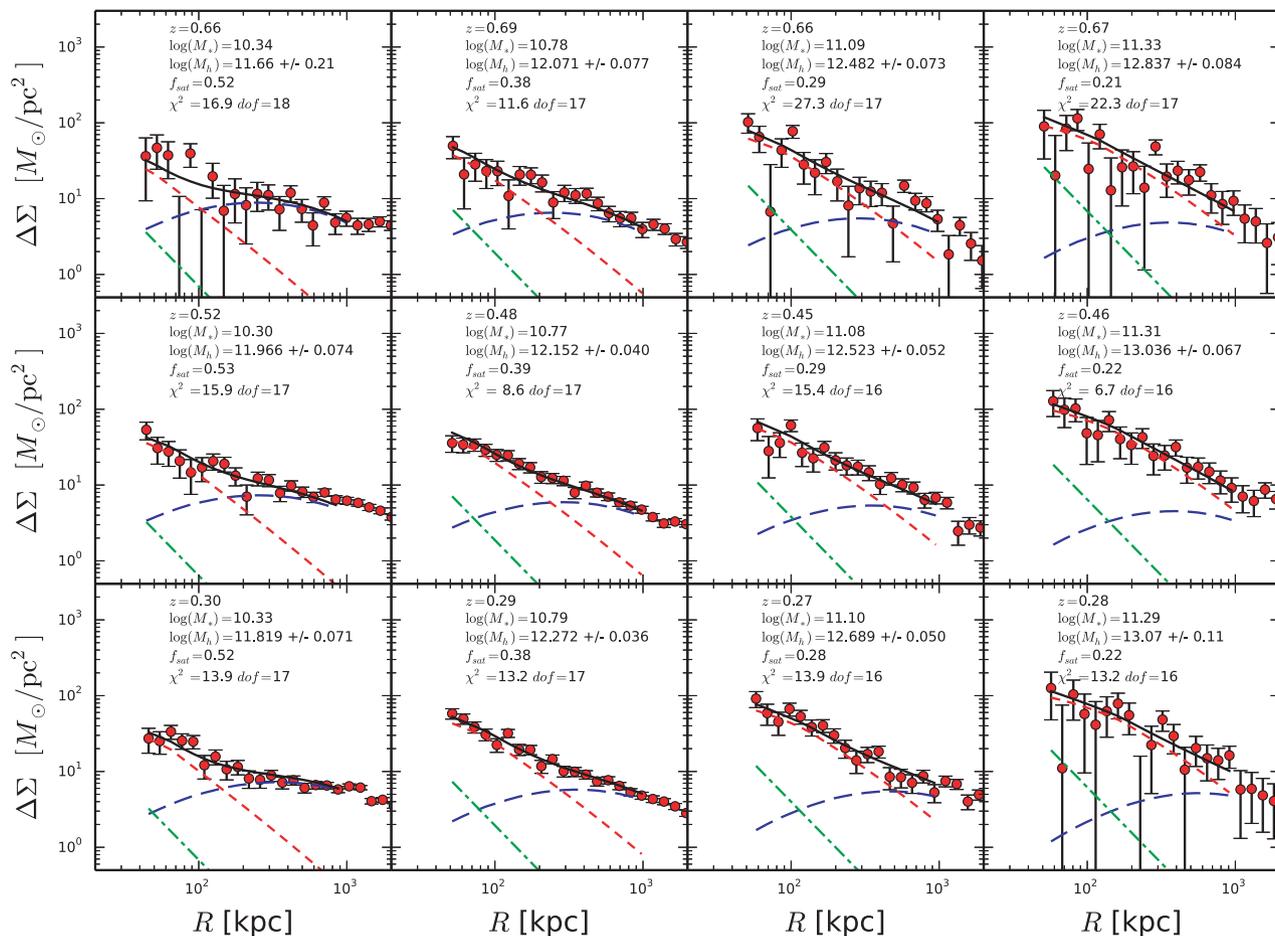


Figure 2. $\Delta\Sigma$ as a function of projected radius for red galaxies. Each panel shows a specific data from a bin in stellar mass and redshift, with redshift decreasing from top ($z \sim 0.7$) to bottom ($z \sim 0.3$) and stellar mass increasing from left to right. The points show the CFHTLenS data. Model fits show the NFW halo (red short-dashed), stellar mass (green dash-dotted) and offset-group halo term (blue long-dashed). The sum is plotted in black. Data are plotted to 2000 kpc, but fits are performed using only data to 1000 kpc.

Note that both of these factors shift the halo masses in the same sense at all redshifts, so the relative evolution is unaffected.

Finally, we chose to fix the satellite fraction to be the same at all redshifts for a given stellar mass and fit this with linear function in log stellar mass. If we allow the satellite fraction to be free at all redshifts, we obtain the results shown in Fig. 5. For blue galaxies, the effect is relatively minor as their satellite fractions are low in any case. For red galaxies, this freedom tends to increase the halo masses (lowering f_*) at $z \sim 0.3$, whereas it decreases the halo masses (raising f_*) in the two higher redshift bins. This will increase the relative evolution between these redshift bins.

In summary, the first two systematics (two-halo term and concentration) are subdominant compared to the random errors. The effect of fitting the satellite fraction is similar to the random errors for most of the red bins (although not for the blue bins for which it is also subdominant).

4.2 Comparison with previous GGL results

In Fig. 6, we compare the results from this paper with the CFHTLenS results from V14. For this comparison, we follow the fitting method of V14 as closely as possible. In particular, first, we allow a free satellite fraction to be fit to each bin independently, and, secondly, we use the concentration–mass relation for all (relaxed

and unrelaxed) haloes (from Duffy et al. 2008), as discussed in Section 4.1. Nevertheless, there remain important differences between the two analyses. The HOD fitting methods differ. In particular, in the V14 analysis, the shape of the offset-group term depends on the fitted halo mass, whereas in the analysis here, the shape of this term is fixed by the HOD of Coupon et al. (2012). Our red/blue division is by colour, whereas that of V14 is by spectral type. We select galaxies in a fixed bin of luminosity (and make a mean correction to M_*), whereas V14 select by M_* (and make a correction for the uncertainty in the measured M_*). Finally, V14 correct for the intrinsic scatter in the SHMR, so that their final data points represent the ‘underlying’ SHMR. In this paper, we prefer to present the GGL data as measured, i.e. representing $\langle M_h | M_* \rangle$, and include the effect of scatter as part of the SHMR model (see Section 5 below). Consequently, Fig. 6 shows the V14 points with their correction for the intrinsic scatter removed (by interpolating from their figure B2 and the values tabulated in their table B3). The results generally agree well.

Fig. 7 shows our results for the SHMR, f_* , as a function of redshift, stellar mass and galaxy type, in comparison with previous results from SDSS by M06. Note that M06 selected galaxies not by colour (as is done for CFHTLenS) but by morphology. While the SDSS data give slightly tighter constraints for rare, very massive galaxies ($M_* \gtrsim 10^{11.5} M_\odot$), the CFHTLenS results are

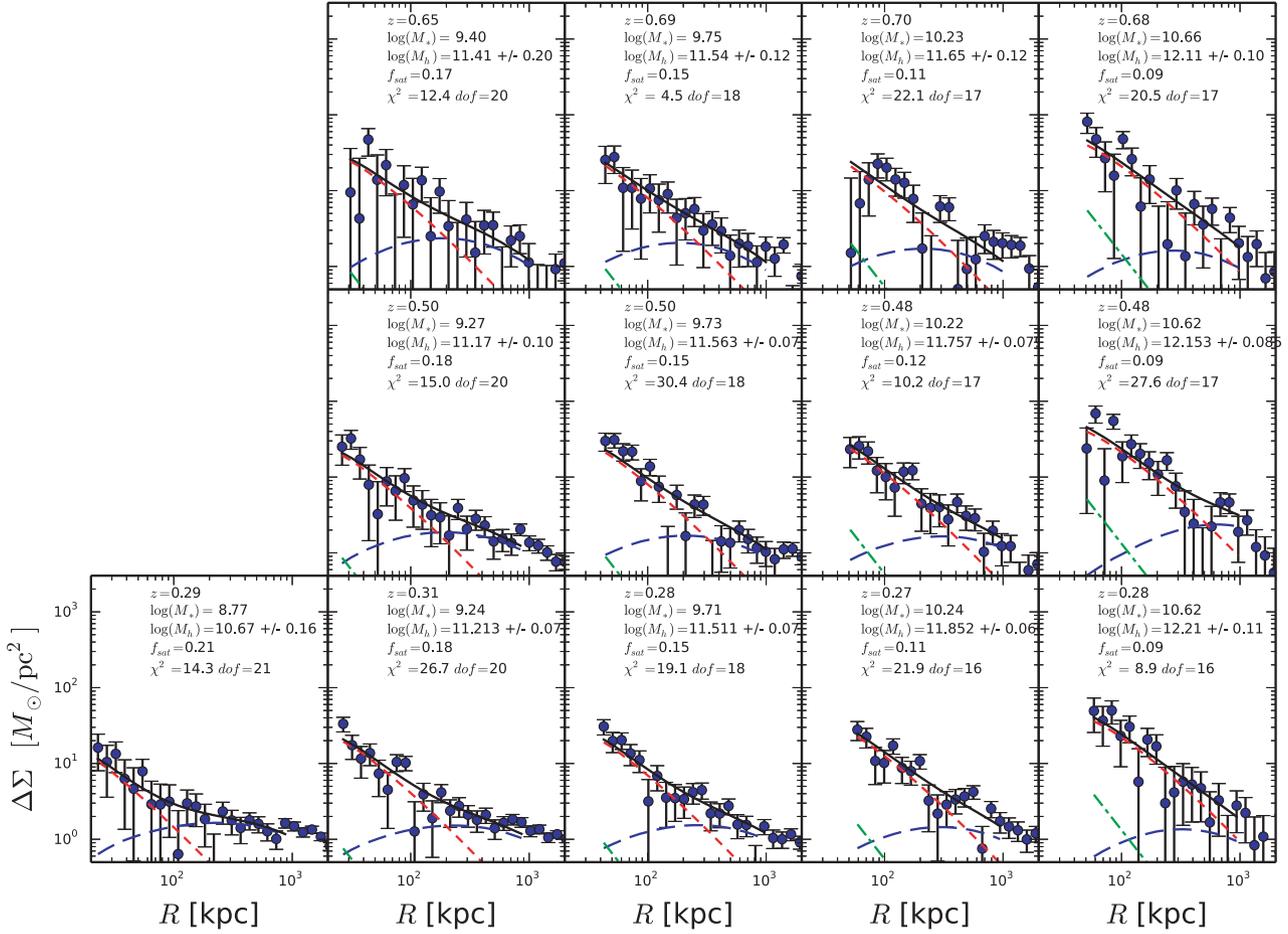


Figure 3. As in Fig. 2 but for blue galaxies.

Table 1. Halo model fits for red galaxies.

N_{lens}	$\langle z_{\text{lens}} \rangle$	$\langle u^* - r \rangle$	$\langle M_r \rangle$	M_* ($10^{10} M_\odot$)	M_h ($10^{11} M_\odot$)	f_{sat}	χ^2	d.o.f.
41 280	0.30	1.81	-20.67	2.14	6.6 ± 1.1	0.523 ± 0.016	13.9	17
33 620	0.28	1.84	-21.71	6.17	18.7 ± 1.6	0.380 ± 0.012	13.2	17
4115	0.27	1.86	-22.60	12.59	48.8 ± 5.6	0.283 ± 0.009	13.9	16
304	0.28	1.87	-23.10	19.50	117.0 ± 29.0	0.223 ± 0.007	13.2	16
66 170	0.52	1.84	-20.60	2.00	9.3 ± 1.6	0.532 ± 0.017	15.9	17
94 590	0.48	1.87	-21.67	5.89	14.2 ± 1.3	0.385 ± 0.012	8.6	17
13 840	0.45	1.89	-22.55	12.02	33.3 ± 4.0	0.289 ± 0.009	15.4	16
1941	0.46	1.91	-23.15	20.42	109.0 ± 17.0	0.217 ± 0.007	6.7	16
48 690	0.66	1.90	-20.69	2.19	4.5 ± 2.2	0.520 ± 0.016	16.9	18
109 100	0.69	1.95	-21.69	6.03	11.8 ± 2.1	0.382 ± 0.012	11.6	17
28 820	0.66	1.95	-22.57	12.30	30.3 ± 5.1	0.286 ± 0.009	27.3	17
7161	0.67	1.98	-23.21	21.38	69.0 ± 13.0	0.210 ± 0.006	22.3	17

considerably tighter for less massive galaxies. Overall, the results agree very well.

Fig. 8 shows a comparison with results from RCS2 (van Uitert et al. 2011). These data are in the redshift range 0.08–0.48. Like the SDSS, the RCS2 is wider and shallower than CFHTLS, so their constraints are tighter for very massive galaxies.

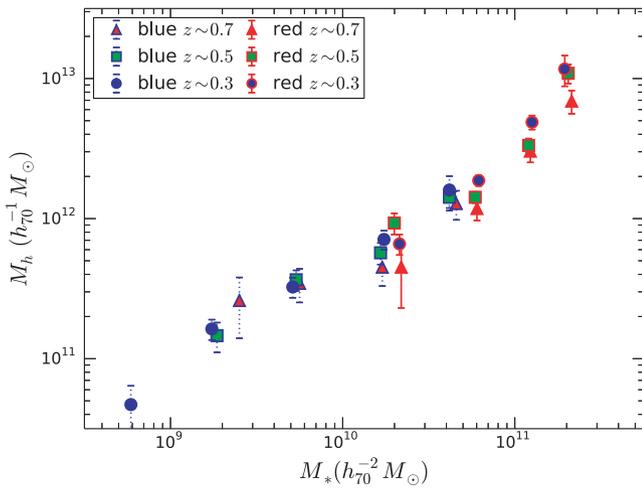
5 THE EFFICIENCY OF STAR FORMATION

5.1 Parametrizing the SHMR

In this paper, we parametrize the dependence of stellar mass on halo mass using the broken double power-law relation (Yang et al. 2003; Moster et al. 2010, hereafter M10):

Table 2. Halo model fits for blue galaxies.

N_{lens}	$\langle z_{\text{lens}} \rangle$	$\langle u^* - r \rangle$	$\langle M_r \rangle$	M_* ($10^{10} M_\odot$)	M_h ($10^{11} M_\odot$)	f_{sat}	χ^2	d.o.f.
215 100	0.29	0.99	-18.18	0.06	0.47 ± 0.17	0.209 ± 0.012	14.3	21
219 400	0.32	1.02	-19.46	0.17	1.63 ± 0.27	0.179 ± 0.010	26.7	20
80 890	0.28	1.15	-20.54	0.51	3.2 ± 0.5	0.148 ± 0.009	19.1	18
30 020	0.27	1.27	-21.55	1.74	7.1 ± 1.1	0.114 ± 0.007	21.9	16
3299	0.28	1.36	-22.39	4.17	16.0 ± 4.1	0.089 ± 0.005	8.9	16
265 900	0.50	0.92	-19.55	0.19	1.46 ± 0.35	0.176 ± 0.010	15.0	20
179 600	0.50	1.09	-20.60	0.54	3.7 ± 0.6	0.147 ± 0.009	30.4	18
73 590	0.48	1.26	-21.51	1.66	5.7 ± 1.0	0.115 ± 0.007	10.2	17
16 900	0.48	1.37	-22.39	4.17	14.2 ± 2.8	0.089 ± 0.005	27.6	17
85 310	0.65	0.83	-19.88	0.25	2.6 ± 1.2	0.168 ± 0.010	12.4	20
239 000	0.69	1.04	-20.64	0.56	3.5 ± 0.9	0.146 ± 0.009	4.5	18
165 700	0.70	1.18	-21.53	1.70	4.5 ± 1.2	0.115 ± 0.007	22.1	17
44 390	0.68	1.32	-22.49	4.57	12.8 ± 3.0	0.087 ± 0.005	20.5	17

**Figure 4.** Fitted halo mass as a function of stellar mass. Blue galaxies are shown by dotted error bars and red galaxies have solid error bars. The symbol type indicates the redshift of the sample, as indicated in the legend.

$$f_*(M_h) = 2f_1 \left[\left(\frac{M_h}{M_1} \right)^{-\beta} + \left(\frac{M_h}{M_1} \right)^\gamma \right]^{-1}. \quad (11)$$

With this parametrization, M_1 is a characteristic halo mass and $f_1 = f_*(M_1)$ is the stellar fraction at that mass. The halo mass at which the SHMR peaks is $M_{h, \text{peak}} = (\beta/\gamma)^{1/(\beta+\gamma)} M_1$. For typical values of β and γ found below, this yields $M_{h, \text{peak}} \sim 0.87 M_1$. To obtain the efficiency of star formation with respect to the mean baryon density, multiply f_* by $\Omega_m/\Omega_{\text{baryon}} = 6.36$ (Planck Collaboration XVI 2014, cosmic microwave background plus BAO). Our fits do not constrain very strongly the high-mass SHMR slope parameter, γ , although they disfavour the M10 value of 0.6, at the $\sim 2\sigma$ level, and prefer higher values. We therefore fix $\gamma = 0.8$ in the following.

We will fit the SHMR parameters allowing f_1 and $\log_{10}(M_1)$ to evolve linearly with redshift. The CFHTLenS lenses are centred at approximately $z = 0.5$, so we Taylor-series expand around this redshift and adopt

$$f_1(z) = f_{0.5} + (z - 0.5)f_z \quad (12)$$

and

$$\log_{10}(M_1)(z) = \log_{10} M_{0.5} + (z - 0.5)M_z. \quad (13)$$

Note that even if M_z is consistent with zero so that there is no dependence of f_* as a function of halo mass (i.e. no halo-mass downsizing), it is still possible to have downsizing in f_* as a function of stellar mass if f_z is significantly different from zero.

Note that the functional form that we have adopted, equation (11), yields the mean SHMR as a function of halo mass. One could plot the SHMR as a function of halo mass $f_*(M_h)$, but in practice this is complicated because the halo mass is the measured quantity with largest uncertainties. This would complicate the plots and uncertainties because halo mass would appear in both the independent and dependent variables. In contrast, the *observational* uncertainty in the stellar mass is negligible compared to that in the halo mass, and so it is more sensible to treat stellar mass as the independent variable.

The complication with using stellar mass as the independent variable is that we expect individual galaxies to scatter around this mean relation (M10). In this paper, we will adopt a scatter of 0.15 dex (following M10 and Behroozi, Conroy & Wechsler 2010), independent of mass, around $f_*(M_h)$. To obtain $\langle M_h | M_* \rangle$, we integrate over the abundance of halo masses and this lognormal scatter:

$$\langle M_h | M_* \rangle = \frac{\int_0^\infty M_h P(M_{*, \text{pred}} | M_*) N(M_h) dM_h}{\int_0^\infty P(M_{*, \text{pred}} | M_*) N(M_h) dM_h}, \quad (14)$$

where $M_{*, \text{pred}} = M_h \times f_*(M_h)$ and P is the lognormal distribution of the stellar mass as a function of the predicted stellar mass and N is the abundance of haloes of mass M_h (Murray, Power & Robotham 2013). For readers who want a simple parametric expression for the estimated halo mass as a function of stellar mass, in Appendix C we present an alternative parametric fit.

5.2 Evolution of red and blue galaxies

We will first discuss the red and blue populations separately. Blue galaxies dominate at low stellar masses whereas red galaxies dominate at high stellar masses. Consequently, there are only two mass bins (in the range $10^{10} M_\odot \lesssim M_* \lesssim 10^{11} M_\odot$) where there are sufficient numbers of both red and blue galaxies in the bin to obtain a halo mass measurement for both the blue and red populations. The independent fits of the M10 double power law given by equation (11) to red and blue populations, both as a function of redshift, are plotted in Fig. 9.

The SHMR fits to blue galaxies are given in Table 3. The SHMR of blue galaxies does not evolve significantly as a function of redshift: the redshift dependence of f_* at fixed mass is only

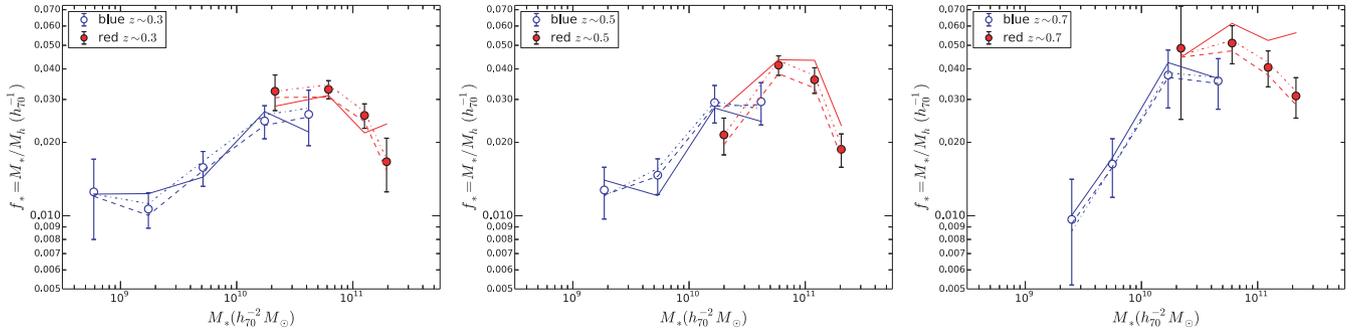


Figure 5. The SHMR f_* as a function of stellar mass for three redshift bins ($z \sim 0.3$, $z \sim 0.5$ and $z \sim 0.7$, from left to right). The round points with error bars show results for our default fit. The lines show the results of different assumptions in the fit, as described in more detail in the text. The dot-dashed line shows the effect of including a two-halo term, the dashed curve uses $c_{200}(M_{200})$ relation for all haloes from Duffy et al. (2008), and the solid curve shows the effect of allowing a free satellite fraction for each bin independently.

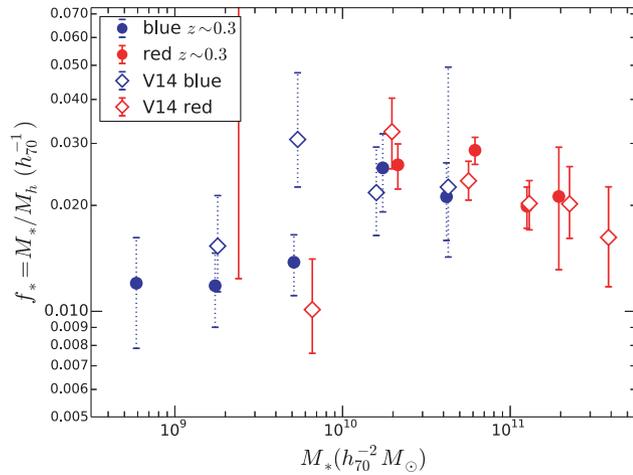


Figure 6. The SHMR as a function of stellar mass. The CFHTLenS results from this paper (but analysed as described in Section 4.2) at $z = 0.3$ are shown by the filled circles and are compared to the CFHTLenS SHMR of V14 (open diamonds), corrected as described in the text. Red galaxies are shown in red and blue galaxies are shown by blue symbols with dotted error bars.

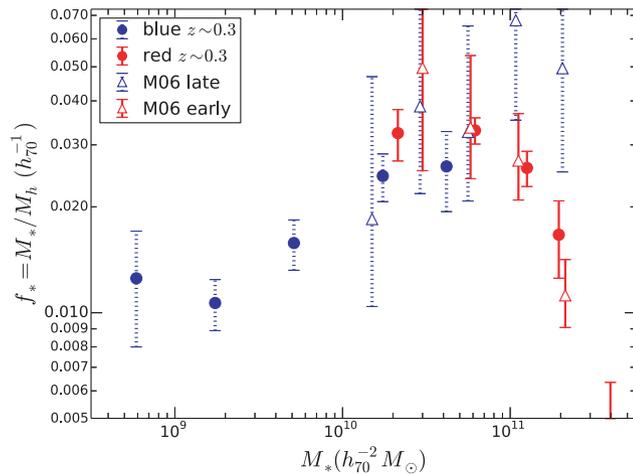


Figure 7. As in Fig. 6, but compared with the SHMR from M06 at $z = 0.1$ (after correction from M_{vir} to M_{200}) for stellar mass bins with lensing signal-to-noise greater than 2 (open triangles). Early-type (SDSS) or red (CFHTLenS) galaxies are shown in red, and late-type (SDSS) or blue (CFHTLenS) galaxies are shown by blue symbols with dotted error bars.

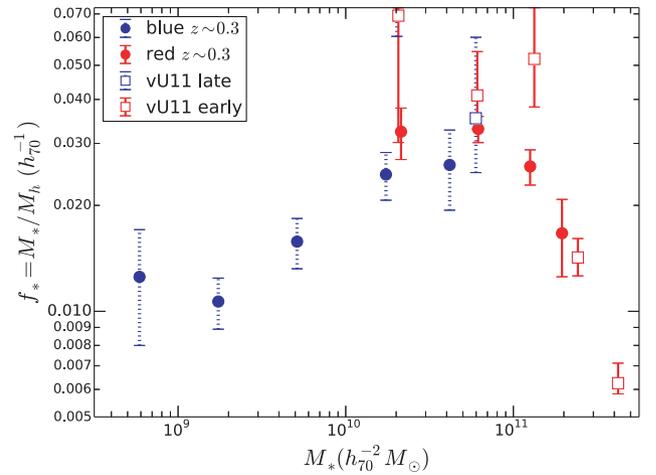


Figure 8. As Fig. 7, but CFHTLenS is compared to the SHMR of RCS2 (van Uitert et al. 2011) indicated by open squares.

$f_z = 0.03 \pm 0.05$, obviously consistent with zero. The best-fitting M10 function has a low-mass slope that is $\beta = 0.55 \pm 0.22$. In this case, the errors on β are large because of partial degeneracies between β and the break mass $M_{0.5}$. A model with no evolution is a good fit. Its χ^2 is larger by only 1.6 with 2 more degrees of freedom (d.o.f.). If, instead, we fit a single power-law SHMR to the blue galaxies (last row of Table 3), the uncertainties on the slope are tighter: $\beta = 0.45 \pm 0.08$, as are the constraints on the evolution: $f_z = 0.028 \pm 0.021$. This is also a better fit than the M10 function, with a χ^2 value larger by only 0.2, but with 2 more d.o.f. Thus, the SHMR of blue galaxies is well described by a non-evolving (single) power law.

In contrast to the blue galaxy population, for the red galaxies a model with no evolution (both $f_z = 0$ and $M_z = 0$, last row in Table 4) is a poor fit ($\chi^2 = 22$ for 9 d.o.f.). The model labelled ‘Default’ in Table 4 has both evolution in the SHMR normalization ($f_z \neq 0$) and evolution in the characteristic halo mass ($M_z \neq 0$). However, it is not a statistically significant improvement over the simpler model with evolution in the normalization but no mass downsizing ($M_z = 0$, labelled ‘No char. halo mass evol.’). Thus, while the downsizing term in halo mass is not significant, the evolution of the normalization is highly significant: $f_z = 0.034 \pm 0.009$. Compared to the ‘No char. halo mass evol.’ model, the no evolution model has $\Delta\chi^2 = 15.2$ for 1 more degree of freedom, and so is formally disfavoured at the 99.99 per cent confidence level (CL), or 3.9σ .

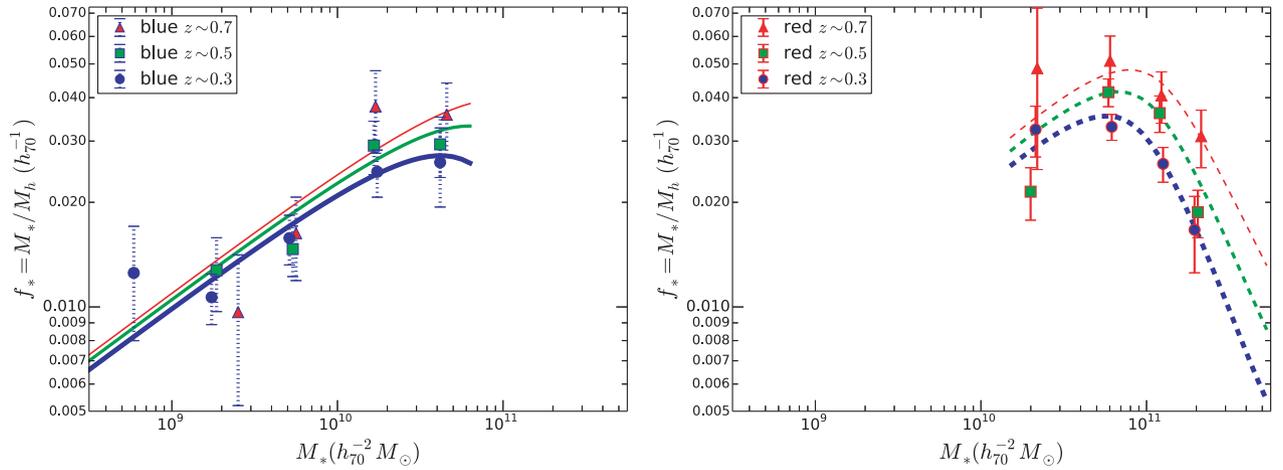


Figure 9. Left: the stellar-to-halo mass ratio (SHMR) as a function of stellar mass for blue galaxies. Data from three different redshift ranges ($z = 0.3, 0.5$ and 0.7) shown in blue circles, green squares and red triangles, respectively). The lines are M10 double power-law fits to the evolution (‘Default’ fit from Table 3), with thickest lines indicating the fit to the lowest redshift bin. Right: same for red galaxies, based on the ‘Default’ fit from Table 4. The evolution is clear: the peak f_* of the red galaxies decreases and shifts to lower stellar masses at later epochs.

Table 3. Double power-law (M10) fits to the SHMR of blue galaxies.

Label	$f_{0.5}$	f_z	$\log(M_{0.5})$	M_z	β	γ	δ_{blue}	χ^2	d.o.f.
Default	0.034 ± 0.010	0.03 ± 0.05	12.5 ± 0.6	0.4 ± 1.5	0.55 ± 0.22	0.8	0.0	7.7	8
No evolution	0.039 ± 0.035	0.00	12.7 ± 1.3	0.0	0.52 ± 0.22	0.8	0.0	9.3	10
Single power law	0.044 ± 0.012	0.028 ± 0.021	13.0	0.0	0.45 ± 0.08	0.8	0.0	7.9	10

Table 4. Double power-law (M10) fits to the SHMR of red galaxies.

label	$f_{0.5}$	f_z	$\log(M_{0.5})$	M_z	β	γ	δ_{blue}	χ^2	d.o.f.
Default	0.045 ± 0.005	0.034 ± 0.012	12.27 ± 0.13	0.00 ± 0.08	0.8 ± 0.5	0.8	0.0	6.8	7
No char. halo mass evol.	0.045 ± 0.004	0.034 ± 0.009	12.27 ± 0.11	0.0	0.8 ± 0.4	0.8	0.0	6.8	8
No peak f_* evol.	0.042 ± 0.007	0.00	12.33 ± 0.19	0.65 ± 0.29	0.7 ± 0.5	0.8	0.0	13.1	8
No evolution	0.043 ± 0.007	0.00	12.28 ± 0.19	0.0	0.9 ± 0.8	0.8	0.0	22.0	9

Table 5. Double power-law (M10) fits to the SHMR of all galaxies.

label	$f_{0.5}$	f_z	$\log(M_{0.5})$	M_z	β	γ	δ_{blue}	χ^2	d.o.f.
Default	0.0414 ± 0.0024	0.029 ± 0.009	12.36 ± 0.07	0.09 ± 0.24	0.69 ± 0.09	0.8	0.0	18.1	20
No char. halo mass evol.	0.0415 ± 0.0024	0.031 ± 0.008	12.36 ± 0.07	0.0	0.68 ± 0.09	0.8	0.0	18.3	21
No peak f_* evol.	0.0411 ± 0.0028	0.00	12.33 ± 0.08	0.49 ± 0.23	0.75 ± 0.12	0.8	0.0	27.9	21
No evolution	0.0399 ± 0.0029	0.00	12.38 ± 0.09	0.0	0.69 ± 0.12	0.8	0.0	33.3	22
With offset	0.0415 ± 0.0025	0.030 ± 0.009	12.36 ± 0.07	0.06 ± 0.24	0.56 ± 0.10	0.8	0.22 ± 0.13	15.3	19

5.3 Fits to all galaxies

Some analyses of the galaxy SHMR do not explicitly distinguish between red and blue galaxies, and so it is interesting to consider the SHMR for all galaxies, independent of their colour. We have fit the red and blue data simultaneously, so each sample is effectively weighted by its inverse square errors. The results of the fits are given in Table 5, and shown in Fig. 10. The red galaxies dominate the peak of the SHMR, so the downsizing effect discussed above is also present here: the peak of the SHMR shifts to lower stellar masses at lower redshifts. A model with no evolution (i.e. a fixed SHMR independent of redshift) has a high $\chi^2 = 33.3$ for 22 d.o.f. As with the red galaxies, the model labelled ‘Default’ that has both evolution in the SHMR normalization and evolution in the characteristic halo mass is a better fit than the ‘No evolution’ model. However, it is not

a statistically significant improvement over the simpler model with evolution in the normalization but no mass downsizing (labelled ‘No char. halo mass evol.’). In the latter model, the redshift dependence of the normalization, $f_z = 0.031 \pm 0.008$, is highly significant. Compared to the ‘No char. halo mass evol.’ model, the no evolution model has $\Delta\chi^2 = 15.0$ for 1 more degree of freedom, and so is formally disfavoured at the 99.99 per cent CL (equivalent to $\sim 3.9\sigma$ significance). For the default fit, the peak f_* drops from 0.045 ± 0.003 at $z = 0.7$ to 0.040 ± 0.002 at $z = 0.5$ and 0.034 ± 0.002 at $z = 0.3$. The stellar mass of the peak ‘downsizes’ from $(7.8 \pm 1.0) \times 10^{10}$ to $(6.7 \pm 0.5) \times 10^{10} M_\odot$ to $(5.6 \pm 0.4) \times 10^{10} M_\odot$ at the same redshifts. As with red galaxies, downsizing in halo mass is not significantly different from zero: $M_z = 0.09 \pm 0.24$. This suggests a picture where the halo mass of $10^{12.25} M_\odot$ is a time-independent peak mass above which the ratio of stellar-to-halo mass declines.

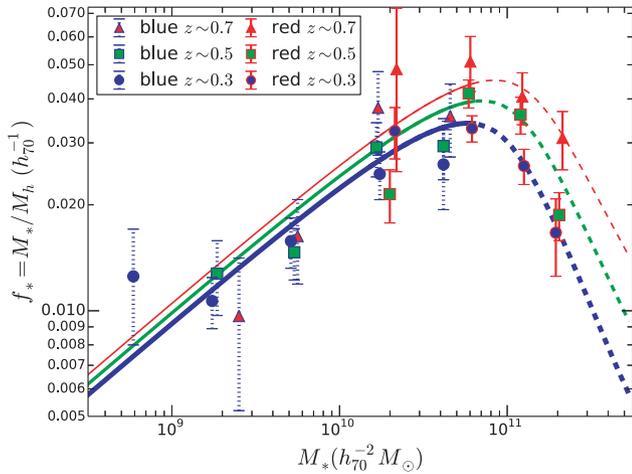


Figure 10. As in Fig. 9, but with a single M10 model fit to both red and blue galaxies simultaneously.

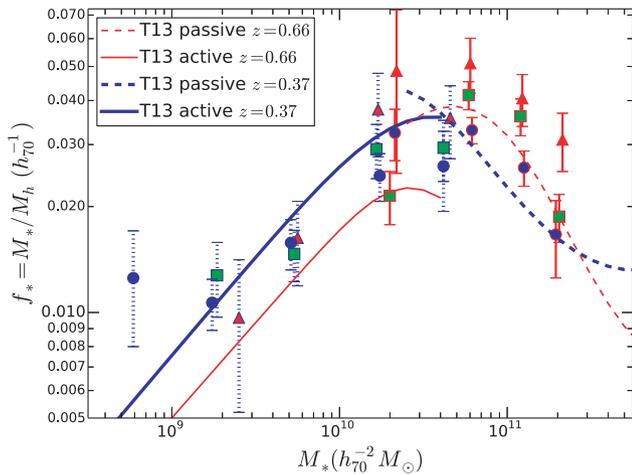


Figure 11. The SHMR for the CFHTLenS sample (symbols as in Fig. 9) compared to the model fits of T13, which are based on a combination of weak lensing, clustering and abundance matching. Compare the thin red $z = 0.66$ dashed and solid lines (for passive and active galaxies, respectively) to the CFHTLenS $z \sim 0.7$ galaxies in red triangles. At lower redshift, compare the $z = 0.37$ model is closest in redshift to the CFHTLenS $z \sim 0.3$ galaxies shown as blue circles.

We saw above that red and blue galaxies may have slightly different SHMRs. There have been suggestions of small differences in the SHMR of red and blue galaxies. Using satellite kinematics, More et al. (2011) found no significant difference between red and blue centrals for stellar masses less than $10^{10.5} M_{\odot}$, but for stellar masses greater than that value, blue galaxies had slightly lower halo masses than red galaxies. Wang & White (2012) find that isolated red galaxies have more satellites (possibly a proxy for halo mass) per unit stellar mass than blue galaxies. However, Tinker et al. (2013, hereafter T13) find that passive (red) galaxies have lower masses than active (blue) galaxies at given M_* (see also Fig. 11 discussed in Section 5.4 below). For the CFHTLenS data, there appears to be no difference between red and blue populations at $M_* \sim 10^{10.3} M_{\odot}$, but the SHMRs of blue galaxies are lower at $M_* \sim 10^{10.7} M_{\odot}$. We have fitted the blue and red populations simultaneously, allowing for an offset term for the halo masses of blue galaxies: $M_{200}(\text{blue}) = (1 + \delta_{\text{blue}})M_{200}(\text{red})$. We find hints of a

difference between blue and red galaxies, with blue galaxies having slightly more massive haloes at fixed stellar mass (in agreement with T13), but the offset is not statistically significant: specifically, $\delta_{\text{blue}} = 0.22 \pm 0.13$.

5.4 Comparison with other results

In Section 4.2, we compared our results to other weak lensing results. Here, we compare our SHMR derived solely from weak lensing with other methods. T13, extending previous work of L12, performed a joint analysis of weak lensing, clustering and abundance for active and passive galaxies in the COSMOS field. Their parametric fits, converted to $f_* = M_*/(M_h|M_*)$, and correcting for their different definition of halo mass (200 times background density), are compared with our weak lensing data in Fig. 11. The approximate peak location and peak heights are comparable, and their low-mass and high-mass slopes are similar for both T13 and CFHTLenS.

We noted in Section 4.1, that there were small systematics associated with the fitting method. In addition, one difference in modelling that can account for some of the discrepancy between T13 and our results is the treatment of partially stripped satellite subhaloes. This issue is discussed in greater detail in Appendix D. There are also systematic uncertainties (at the level of 0.2 dex) associated with the stellar mass estimates, both for our sample and that of T13.

On the other hand, the evolution of the SHMR is a differential measurement, and so we expect it to be more robust to systematic uncertainties than the absolute value of the SHMR. The fits of T13 indicate that there is evolution in the low-mass blue galaxy SHMR (compare the $z = 0.37$ SHMR with the $z = 0.66$ SHMR in Fig. 11) that we do not observe. L12 also suggested that evolution of the SHMR evolution could be described by a model in which the peak star formation efficiency did not depend on redshift, but where the peak (‘pivot’) halo mass decreased with time. In our fits (Table 5), such models are labelled ‘No peak f_* evol.’ and are generally disfavoured at the $\sim 2\sigma$ level in comparison to models in which the normalization (and hence the peak f_*) depends on redshift. While we do find downsizing in the peak stellar mass, we do not find significant evidence for downsizing in the location of the peak halo mass from our CFHTLenS data.

Behroozi, Wechsler & Conroy (2013) compiled data on the stellar mass function, the specific star formation rate and the cosmic star formation rate from a number of sources and used abundance matching to fit the SHMR and its evolution over a wide range of redshifts. In Behroozi et al. (2010), the systematic uncertainties in abundance matching are discussed in detail. The largest of these, the uncertainty in stellar mass estimates, leads to systematic uncertainties in the SHMR of order 0.25 dex. The fits of Behroozi et al. (2013) are overlaid on the CFHTLenS data in Fig. 12. Although their models underpredict the CFHTLenS f_* for red galaxies (particularly at higher redshift), the difference is within the 0.25 dex uncertainty. The overall shape of the SHMR and its dependence on redshift are similar to those observed in the CFHTLenS data. In particular, the low-mass slope and the weak evolution of the SHMR of faint blue galaxies are consistent with the shallow β and its lack of evolution. Although offset from the GGL data at masses greater than the peak mass, their model predicts evolutionary trends at high mass that are consistent with what we observe, albeit with less evolution than we find. Specifically, at fixed stellar mass $M_* = 10^{11} M_{\odot}$, the evolution predicted by their model is $f_*(z = 0.7)/f_*(z = 0.3) = 1.23$, whereas we find $f_*(z = 0.7)/f_*(z = 0.3) = 1.36 \pm 0.09$.

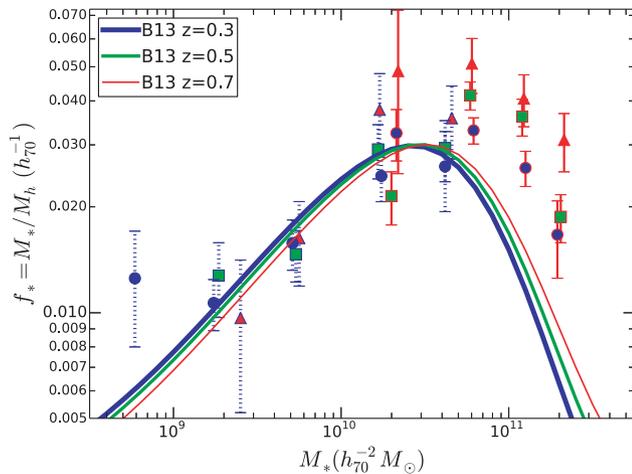


Figure 12. The SHMR for the CFHTLenS sample (symbols as in Fig. 9) compared to the abundance matching fits of Behroozi et al. (2013) as indicated in the legend.

5.5 Faint blue dwarfs

The power of the CFHTLenS sample allows us to measure the DM halo masses of faint blue galaxies, with mean luminosities $M_r \sim -18$ or, equivalently, stellar masses $M_* \sim 10^{8.75} M_\odot$ (similar to the Small Magellanic Cloud). This is the first time that weak lensing masses have been obtained for such faint dwarfs. For these faint blue dwarf galaxies, the observed SHMR deviates from simple power-law extrapolations from higher masses, as well as from the predictions of abundance matching. This deviation has been noted by Boylan-Kolchin, Bullock & Kaplinghat (2012, see fig. 9), who showed from dynamical measurements that low-mass galaxies ($M_* < 10^9 M_\odot$) lie off the predictions of abundance matching. A similar conclusion was reached by Ferrero et al. (2012). The latter authors note that the conflict between masses estimated via rotation curves and those predicted from abundance matching could be resolved if, for some reason, rotation velocities underestimate the circular velocities.

In Fig. 13, we show the SHMR derived from galaxy rotation curves at $z \sim 0$, compiled by Ferrero et al. (2012). While there is considerable scatter in the SHMR from galaxy-to-galaxy, the medians of the data have a power-law slope is $\beta \sim 0.5$. This is in good agreement with the mean lensing SHMR for blue galaxies, which has a power-law slope $\beta = 0.44 \pm 0.08$ (last row of Table 3). There may be a small offset of ~ 25 per cent with halo masses from lensing being slightly smaller, so it does not seem as if the problem lies on the rotation curve underestimating halo masses.

6 DISCUSSION

6.1 Understanding evolution in the SHMR diagram

The SHMR diagram is the ratio of stellar to DM mass, as a function of stellar mass. Therefore, any process that affects either the stellar mass or the DM halo mass will move the location of a galaxy in this diagram. The first such process is DM accretion: DM haloes, provided they are ‘centrals’ and not ‘satellites’ or subhaloes, will accrete matter from their surroundings, either smoothly or from mergers of smaller haloes. This is well understood from N -body simulations in the Λ CDM model. The downward pointing arrows in Fig. 14 show the effect of DM accretion, based on the mean

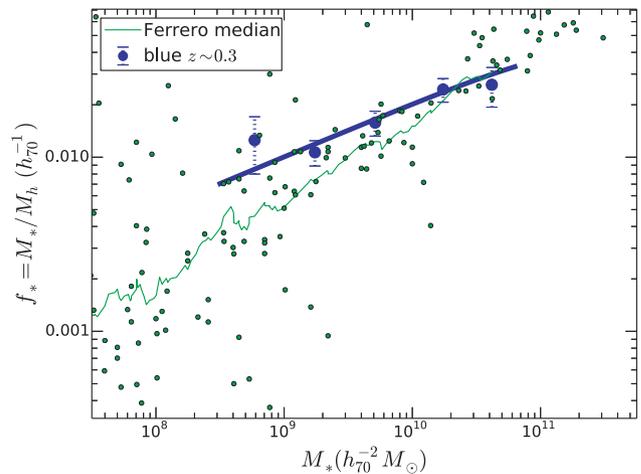


Figure 13. The SHMR for blue dwarfs at low redshift. Note that the plot extends to lower stellar masses than previous figures. The small green dots show estimates based on $z \sim 0$ rotation curves from the compilation of Ferrero et al. (2012). The jagged green line is a running median of these data. The blue data points with error bar and dotted blue line show the weak lensing data at $z \sim 0.3$.

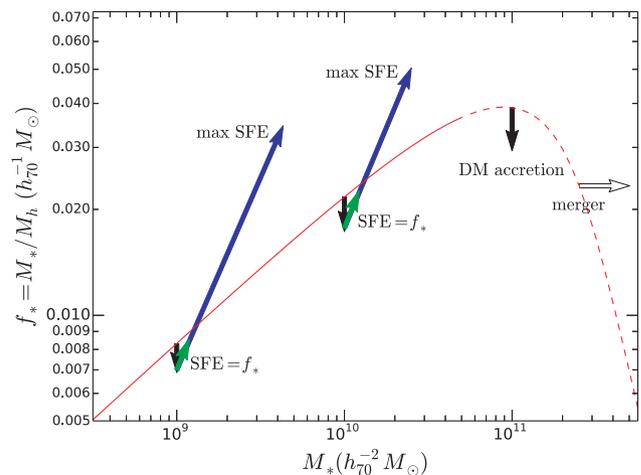


Figure 14. Physical processes that affect the evolution in the SHMR. The curve shows the SHMR at $z = 0.7$. Arrows show various processes that affect the evolution of DM or stellar mass or both, extrapolated from $z = 0.7$ to 0.3 . The black downward pointing arrows show the effects of DM accretion based on Fakhouri et al. (2010), for haloes of three different masses. The diagonal coloured arrows show the effect of star formation: the long blue arrow shows the maximal amount of star formation, i.e. one where all accreted baryons are converted to stars. In this case, the SHMR relation itself evolves to higher f_* at given M_* . The short green diagonal arrow shows the effect of star formation assuming the efficiency is the same as f_* . In the latter case, the net effect of DM accretion and star formation is to move the galaxy to higher stellar mass at the same f_* . The white arrow shows the effect of the merger of two identical galaxies in identical haloes: f_* is unchanged but the stellar mass increases.

mass accretion history of Fakhouri, Ma & Boylan-Kolchin (2010, equation 2), which is a function of halo mass and redshift.

Star formation creates stellar mass and moves a galaxy in Fig. 14 on an upward diagonal line with slope one. In the current picture of galaxy formation, blue galaxies progress along a star-forming sequence, with decreasing specific star formation rates as their stellar masses increase (Brinchmann et al. 2004). The sequence itself, i.e. the specific star formation rate at a given stellar mass also

evolves towards lower specific star formation rates as a function of increasing cosmic time (Noeske et al. 2007). Therefore, we expect blue galaxies that are star-forming to evolve in the SHMR diagram. The blue galaxies are almost all central galaxies, and so they will also accrete DM. Therefore, whether these galaxies move to the right of the SHMR locus, along the locus or above it depends on the balance between the star formation rate and the DM halo accretion rate. Three scenarios are plotted in Fig. 14.

Once star formation is quenched, there are two possibilities: either a galaxy becomes a satellite, or it remains a central. In the former case, we expect the DM halo to be stripped, in which case the ratio f_* should increase, provided the denominator M_h is the actual DM halo mass. However, in the analysis in this paper, the predicted $\Delta\Sigma$ already assumes that the satellites have been partially stripped (equation 9) and so the fitted parameter M_{200} actually represents the pre-stripped mass. Therefore, we expect no change due to stripping given our definition of f_* .

If the red galaxy is a central galaxy, then the DM halo will continue to grow by accretion of DM and haloes. For the evolution of the stellar mass, there are two possibilities. If the galaxies in the accreted haloes become satellite galaxies, then the stellar mass of the central galaxy remains unchanged and so the ratio f_* will decrease as their stripped halo mass is added to the central DM halo. On the other hand, if these galaxies merge with the central, then this will boost the stellar mass of the central. For example, if two identical galaxies in identical haloes merge, they will both be combined into a single point that is shifted horizontally to the right by $\log_{10}(2) = 0.301$ in Fig. 14. Of course, in reality, nearly all mergers will be less than 1:1 in mass ratio so the effect will be smaller, and in general, will not be of two galaxies with equal initial f_* .

6.2 Towards a physical model for SHMR evolution

The fitted SHMR and its evolution, presented in Section 5, is a purely parametric model without a physical basis. As discussed above, we can model some of the physical processes that move a galaxy in the SHMR diagram as a function of time. While a galaxy is on the blue sequence, the dominant processes are DM accretion and star formation. While it is forming stars it must move to the right in the diagram, but as discussed above, how much it moves vertically depends on the balance between star formation and DM accretion. At some point, star formation is quenched. Observations suggest that, at least at the high masses studied here, the dominant quenching process is not environmental but rather ‘internal’ to the galaxy itself (Peng et al. 2010).

The star formation rates of star-forming galaxies have been well studied empirically. In most fits, star formation rate is a function of stellar mass and redshift. As a fiducial model, we adopt the star formation model of Gilbank et al. (2011). We assume that a fraction 0.6 of the newly formed stars are retained as long-lived stars after stellar mass loss (supernovae, stellar winds; Baldry, Glazebrook & Driver 2008). The quenching mechanism may depend simply on the stellar or halo mass of the galaxy, or a different property such as the star formation rate (Peng et al. 2010) or stellar density. The ‘downsizing’ phenomenon suggests that it may also depend explicitly on redshift. As an example, we model quenching as a simple stellar-mass-dependent and redshift-dependent function. Moustakas et al. (2013) find that the transition or crossover mass (where the number of red and blue galaxies is equal, or, equivalently, where the quenched fraction is 0.5) scales with redshift as $(1+z)^{1.5}$ and has a value $10^{10.75} M_\odot$ at $z = 0.7$, consistent with Pozzetti et al. (2010).

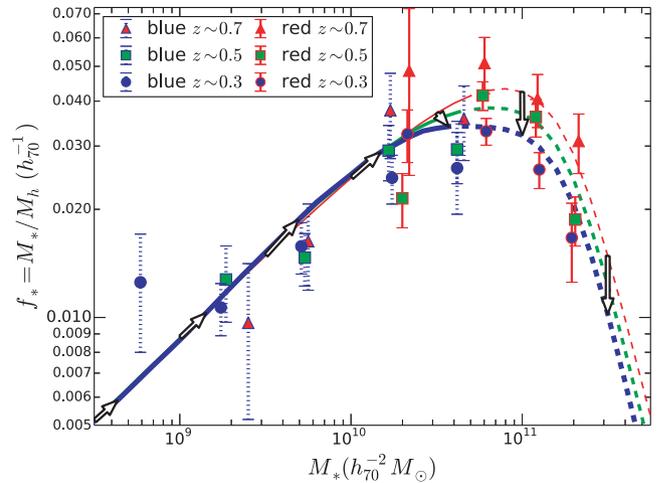


Figure 15. SHMR data compared to a model in which star formation follows the empirical star formation prescription and an empirical quenching prescription (see text for details). Large arrows show the evolutionary tracks of individual galaxies of different stellar masses as they evolve from $z = 0.7$ to 0.3. Notice that blue galaxies evolve *along* the SHMR relation. Red galaxies have a decreasing f_* , consistent with that expected from pure DM accretion.

Since we have no physical model for the initial ($z = 0.7$) SHMR, this is fitted with a M10 double power law. Galaxies more massive than $M_* \sim 10^{10.75} M_\odot$ are assumed to be quenched. Subsequent evolution to $z = 0.5$ and 0.3 is given by the DM accretion, star formation and quenching prescriptions described above. This model therefore has only four free parameters, fewer than the parametric fits in Section 4. The results are shown in Fig. 15. Overall, the model reproduces the trends seen in the data. The fit has $\chi^2 = 20$, statistically equivalent to the best parametric models in Table 5, given that this model has two fewer free parameters.

The evolution of star-forming galaxies is particularly interesting. The star formation rates from Gilbank et al. (2011) balance the mean DM halo accretion rates from Fakhouri et al. (2010) in such a way that galaxies evolve mostly *along* the SHMR relation, with only a small amount of vertical offset that is consistent with the observational uncertainties. There is no a priori reason that these two functions had to balance in just this way. Thus, the evolution of the SHMR can be used to understand the mean star formation history.

7 CONCLUSIONS

The depth and area of the CFHTLS has allowed us to study the relationship between stellar and halo mass in red and blue galaxies over a wider range of stellar mass and redshift than was heretofore possible with weak lensing. The main conclusions are:

- (i) From weak lensing alone, we confirm that the SHMR peaks at halo masses $M_h = 10^{12.23 \pm 0.03} M_\odot$ with no significant evolution in the peak halo mass detected between redshifts $0.2 < z < 0.8$.
- (ii) The SHMR does evolve in the sense that the peak SHMR drops as a function of time. This result is formally statistically significant at the 99.99 per cent CL for our parametric model. As the peak halo mass remains constant, this means that it is the peak stellar mass which is evolving towards lower stellar masses as the galaxy redshift decreases. This is consistent with a simple model in which the stellar mass at which galaxies are quenched evolves towards a lower stellar mass with time.

(iii) The population of blue galaxies does not evolve strongly in the SHMR diagram. This implies that their star formation balances their DM accretion so that individual galaxies move along the SHMR locus with cosmic time.

(iv) For the first time, weak lensing measurements of the halo mass extend to blue dwarf galaxies as faint as $M_r \sim -18$, with stellar masses comparable to the Magellanic Clouds. The relatively flat power law of the SHMR of blue galaxies as a function of stellar mass that was noted previously via studies of rotation curves is present in the weak lensing SHMR as well.

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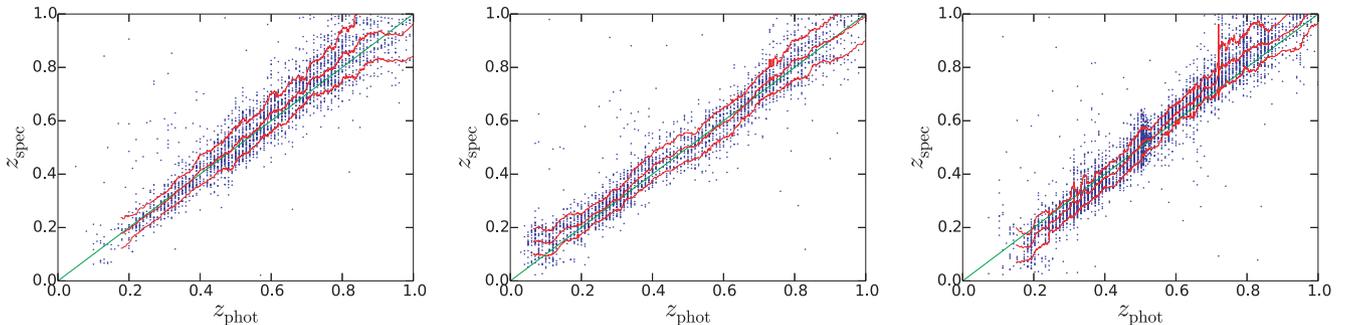


Figure A1. Spectroscopic redshifts (compiled by Hildebrandt et al. 2012) as a function of photometric redshift for different spectral types. The left-hand panel shows $T < 1.75$, the middle panel $1.75 \leq T < 2.9$ and the right-hand panel is for $T \geq 2.9$.

APPENDIX A: CORRECTIONS FOR BIAS IN THE PHOTOMETRIC REDSHIFTS

The photo- z 's used in this paper have small biases compared to spectroscopic redshifts (typically within the range ± 0.03), as noted by Hildebrandt et al. (2012). We have recomputed these biases for the range of redshifts, magnitudes and spectral types used here. The comparison are shown in Fig. A1, for three spectral types $T < 1.75$, $1.75 \leq T < 2.9$ and $T \geq 2.9$. The middle jagged red line is a running mean of z_{spec} as a function of z_{phot} after clipping 3σ outliers. The upper and lower red lines indicate the running standard deviation (also after clipping).

The bias appears to be roughly linear function of z_{phot} , except for the late-type panel, in which there is a discontinuity at $z \sim 0.5$. We correct this discontinuity by hand, and then fit a linear function to the clipped means to determine corrected redshifts. After correction, the corrected z_{phot} lie within ± 0.01 of z_{spec} .

These bias corrections are applied to the lens galaxy redshifts. We do not apply corrections to the source sample, as the latter are fainter than the spectroscopic sample. The comparisons in Hildebrandt et al. (2012) show that the bias is generally not a monotonic function of magnitude, so extrapolating from the brighter lenses to the fainter sources might be dangerous. They also show that at the faintest magnitudes, corresponding to the CFHTLenS sources, the bias appears to be small.

APPENDIX B: CORRECTIONS FOR SCATTER IN THE PHOTOMETRIC REDSHIFTS

Here, we describe the corrections to the observables that are necessary because of the fact that photometric redshifts have scatter $\sim 0.04(1+z)$. As emphasized by Nakajima et al. (2012) and Choi et al. (2012), this scatter leads to Eddington-like biases in several quantities of importance for weak lensing: the mean redshifts of the lenses and consequently the mean luminosities and stellar masses of the lenses, as well as the D_{ls}/D_s ratio. While the CFHTLenS photo- z scatter is less than the SDSS photo- z scatter ($0.096(1+z)$) studied by Nakajima et al. (2012), it is nevertheless important to include these corrections.

We simulate these effects by using mock galaxy populations with known redshift and luminosity distributions, then scattering their true redshifts and re-calculating all quantities that depend on this redshift (luminosity, stellar mass, D_{ls}/D_s ratio and so on). We then select lens samples in bins of (scattered) luminosity and redshift (as is done for the CFHTLenS sample) and so determine the bias in these quantities that arises from the scatter in the photometric redshifts.

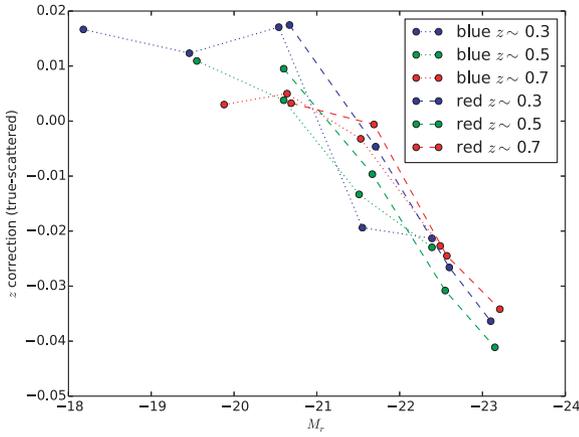


Figure B1. True lens redshift minus mean lens redshift after scattering by photo- z uncertainties, as a function of (scattered) magnitude and (scattered) redshift.

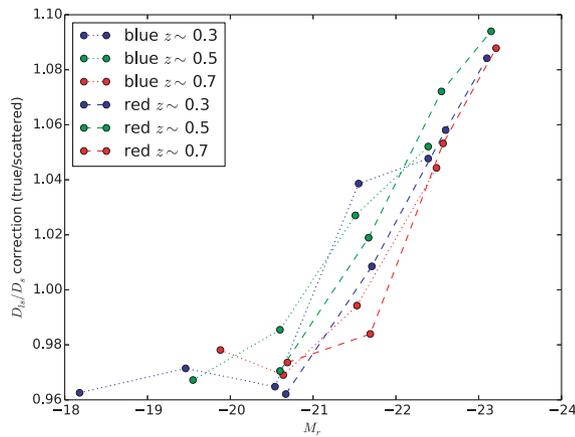


Figure B2. As in Fig. B1 but for the ratio of the true D_{ls}/D_s ratio to its value after redshift scattering.

Specifically, we select galaxies from light-cones samples of Henriques et al. (2012) based on the semi-analytic models of Guo et al. (2011). Henriques et al. (2012) show that these are excellent fits to the observed number counts, $n(z)$ and luminosity functions over the ranges covered by the CFHTLenS lens sample ($i'_{AB} < 23$, $0.2 < z < 0.8$).

The corrections derived in this way are shown in Figs B1, B2 and B3 for lens redshift, D_{ls}/D_s , and lens luminosity, respectively.

APPENDIX C: SHMR AS A FUNCTION OF M_*

For consistency and ease of comparison with previous work, the fits presented in Section 5 are based on a parametrization of f_* as a function of halo mass, M_h . For many practical purposes (e.g. Hudson, Harris & Harris 2014), however, one wants instead the halo mass as a function of stellar mass. While it is possible to use equation (14) to obtain M_* as a function of M_h and invert this numerically, this requires knowledge of the halo mass function and so it is more complicated to implement numerically.

In order that readers may easily obtain the halo mass as a function of stellar mass, in this section, we give fits to a modified version of

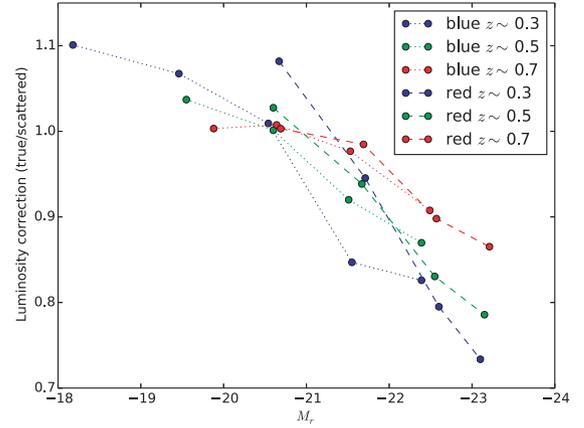


Figure B3. As in Fig. B1 but for the ratio of true lens luminosity to its value after redshift scattering.

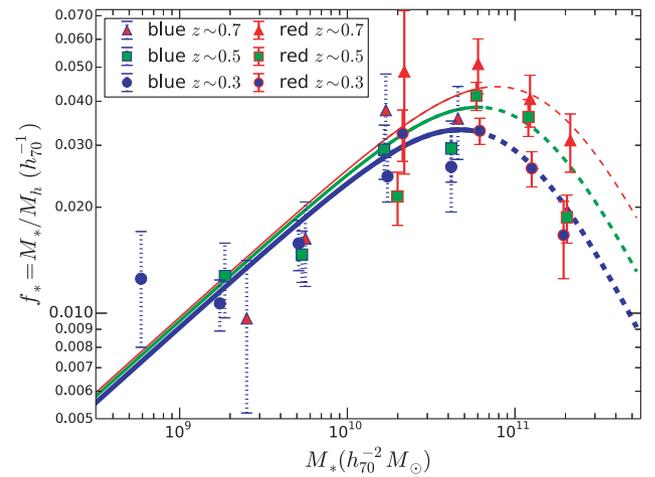


Figure C1. As in Fig. 10, but the plotted lines are based on parametric form given in equation (C1), and use the ‘Default’ parameters of Table C1.

equation (11), in which the SHM ratio is a function of stellar mass M_* . Specifically, equation (11) is replaced with

$$f_*(M_*) = 2f_1^* \left[\left(\frac{M_*}{M_1^*} \right)^{-\beta^*} + \left(\frac{M_*}{M_1^*} \right)^{\gamma^*} \right]^{-1}, \quad (\text{C1})$$

where the ‘*’ superscript reminds the reader that the fit is based on stellar mass, not halo mass. As before we express these parameters as a function of redshift as follows

$$f_1^*(z) = f_{0.5}^* + (z - 0.5)f_z^* \quad (\text{C2})$$

and

$$\log_{10}(M_1^*(z)) = \log_{10} M_{0.5}^* + (z - 0.5)M_z^*. \quad (\text{C3})$$

In this section, we fix $\gamma^* = 1$, for which the asymptotic behaviour is $M_h \rightarrow \text{constant}$ as $M_* \rightarrow \infty$. The fits actually prefer a steeper $\gamma^* \sim 1.5$, but this choice of γ^* would lead to a non-monotonic behaviour in which M_h rises, reaches a maximum and then declines as $M_* \rightarrow \infty$. The fit with $\gamma^* = 1$ is only marginally worse (at the $\sim 2\sigma$ level), and avoids this undesirable, non-physical behaviour.

The results of the fit are shown in Fig. C1 and Table C1. The quality of the fit is similar to the fits as a function of M_h , and qualitatively the results are similar as found in above, namely that evolution is required at a high significance level.

Table C1. Double power-law fits using equations (C1)–(C3) to the SHMR of all galaxies.

Label	$f_{0.5}^*$	f_z^*	$\log(M_{0.5}^*)$	M_z^*	β^*	γ^*	δ_{blue}^*	χ^2	d.o.f.
Default	0.0357 ± 0.0022	0.026 ± 0.009	11.04 ± 0.09	0.56 ± 0.33	0.43 ± 0.05	1.0	0.0	22.0	20
No char. stel. mass evol.	0.0350 ± 0.0022	0.026 ± 0.009	11.05 ± 0.09	0.0	0.40 ± 0.05	1.0	0.0	25.0	21
No peak f_* evol.	0.0355 ± 0.0025	0.00	10.98 ± 0.09	0.65 ± 0.33	0.47 ± 0.06	1.0	0.0	32.2	21
No evolution	0.0340 ± 0.0023	0.00	11.07 ± 0.11	0.0	0.42 ± 0.06	1.0	0.0	36.3	22
With offset	0.0369 ± 0.0025	0.026 ± 0.008	11.00 ± 0.09	0.51 ± 0.30	0.38 ± 0.05	1.0	-0.22 ± 0.09	17.9	19

APPENDIX D: TREATMENT OF STRIPPED SATELLITE SUBHALOES

In Section 3.1, we discussed our default model in which satellites have subhaloes of their own. As described there, these the DM satellite subhaloes are assumed to be partially tidally stripped. Indeed, by comparing the weak lensing signals of satellites and field galaxies of the same stellar mass in CFHTLenS, Gillis et al. (2013) found that, on average, satellites had 35 ± 12 per cent of their mass stripped. We assume the same stripping scheme as some previous studies (M06, V14). Thus, when one stacks the lensing signal around a mixed population of a given stellar mass, the predicted DM signal is

$$\Delta \Sigma_{\text{th,DM}} = (1 - f_{\text{sat}}) \Delta \Sigma_{\text{iNFW}}(M_{200}, c) + f_{\text{sat}} \Delta \Sigma_{\text{iNFW}}(M_{200}, c). \quad (\text{D1})$$

where $\Delta \Sigma_{\text{iNFW}}(M_{200}, c)$ is given by equation (9).

The treatment of satellite subhaloes is different in some works. In particular, L12, T13 and Coupon et al. (submitted) omit the satellite subhalo term in their lensing models, equivalent to assuming the satellites are completely stripped, or to setting $\Delta \Sigma_{\text{iNFW}}(M_{200}, c) = 0$. Thus, in comparison to the results presented here, for the same weak lensing measurements, the fitted mass is correspondingly increased by a factor $\sim (1 + f_{\text{sat}})^{-1}$.

To test the effect of the treatment of satellite subhaloes, we can emulate the fits of L12, T13 and Coupon et al. by also setting the satellite subhalo term $\Delta \Sigma_{\text{iNFW}}(M_{200}, c) = 0$. The results of this modified fit for the CFHTLenS data are shown in Fig. D1 for the subsample of red galaxies with $z \sim 0.7$. As expected, the modified fits yield higher fitted NFW masses and hence lower f_* in good agreement with red galaxies from T13. The importance of this term depends on the satellite fraction, which varies from as high as 0.85 for passive low-mass satellites at high redshift to ~ 0 for massive active centrals. Furthermore, the fits of L12, T13

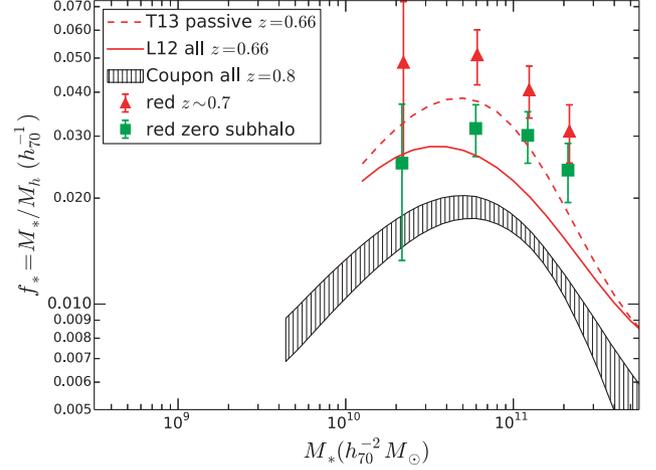


Figure D1. SHMR for CFHTLenS red galaxies at $z \sim 0.7$ comparing the estimated halo mass including the default assumption that satellites have partially stripped subhaloes (red triangles) and setting their subhalo contribution to zero (green squares). The latter assumption is adopted in the GGL analysis of T13, L12 and Coupon et al., whose fits are shown by the dashed red line (passive galaxies), solid red line (all galaxies) and hatched area (all galaxies), respectively.

and Coupon et al. also include abundance matching and galaxy correlation functions in addition to GGL, and indeed these may dominate over noisier GGL signal. Thus, even were these authors to replicate our assumptions regarding tidal stripping, it is not clear that their fits would be as affected by this choice as are our GGL-only fits.

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