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Interaction between deformation and sedimentation in a multidecollement thrust zone: analogue modelling and application to the Sub-Andean thrust belt of Bolivia

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ABSTRACT

Fold and thrust belts are influenced by the presence of decollement levels, as well as the amount of shortening and synkinematic sedimentation. These parameters are studied at the scale of a thrust belt using a field approach, combined with analogue and numerical modelling. In this study, we use analogue modelling to test the evolution of a single structure during sedimentation in a domain containing three prekinematic decollement levels. The development of this structure in the analogue experiments shows that the expression of the deformation is strongly dependent on sedimentation rate: (i) the structure propagates forward in an overall asymmetric shape if the sedimentation rate is slower than the uplift velocity, or (ii) the structure grows vertically and its vergence changes at the surface if the sedimentation rate is similar to the uplift velocity, or (iii) the structure grows
vertically with a double vergence at the surface and at depth if the sedimentation rate is higher than the uplift velocity. The results of the experiments are compared with structures in the Subandean thrust belt to aid the interpretation of poor seismic data.

1. Introduction

The deformation observed in compressive systems such as fold and thrust belts is influenced by the presence of decollement levels (e.g. Dunn et al., 1995; Labaume and Moretti, 2001; Sepehr et al., 2006; Verges et al., 2011), which exhibit low basal friction related to lithology (marl, shale, coal and evaporite) and/or overpressure conditions (e.g. Cobbold and Rodrigues, 2007; Cobbold et al., 2009). These systems have been investigated in previous analogue studies that show the importance of the basal angle of the wedge and the shortening rate (e.g. Smit et al., 2003), as well as the presence of decollement levels in controlling coupling/decoupling processes (e.g. Couzens-Schultz et al., 2003; Massoli et al., 2006) and synkinematic sedimentation (Leturmy et al., 2000). The relationship between sedimentation and thrust geometry at the scale of a single structure has been studied using analogue modelling with one prekinematic ductile layer (Nalpas et al., 1999; Casas et al., 2001; Barrier et al., 2002; Nalpas et al., 2003; Gestain et al., 2004; Barrier et al., 2013). However, only one study has been carried out at the scale of a single structure with two prekinematic ductile layers (Pichot and Nalpas, 2009), so there is a continuing debate about the vergence of the thrusts as well as the evolution of deformation at depth and at the surface in relation to mass transfer.

This study makes use of analogue modelling to investigate the formation and evolution of a compressive structure with a mechanical stratigraphy comprising three prekinematic decollement levels (ductile layers) according to (i) the amount of shortening and (ii) the synkinematic rate of mass transfer. The results of this experimental approach are then compared with a field example (the Subandean thrust-belt).

2. Experimental procedure

In this study, we apply the classical techniques used for brittle-ductile analogue modelling experiments developed by the Experimental Tectonics Laboratory of Géosciences Rennes (Université de Rennes 1, France). These techniques have been described in previous studies dealing
with the use of a velocity discontinuity (VD; e.g. Malavieille, 1984; Balé, 1986; Ballard et al., 1987; Allemand et al., 1989), the use of silicone and sand (Faugère and Brun, 1984), and also various scaling issues (Davy and Cobbold, 1991; Weijermars et al., 1993). Brittle layers (pre- and synkinematic) are represented by dry Fontainebleau quartz sand, with an internal friction angle of 30-35° (Krantz, 1991) and a density ($\rho$) of approximately 1,500 kg/m$^3$. The weak ductile layers (e.g. salt, clay) are represented by i) pink silicone putty 70 009 (Rhône Poulenc, France) with a viscosity ($\mu$) of around $10^4$ Pa·s at 20°C and a density ($\rho$) close to 1,400 kg/m$^3$, and ii) transparent silicone putty SGM 36 (Dow Corning, USA) with a viscosity ($\mu$) of around $10^4$ Pa·s at 20°C and a density ($\rho$) close to 1,000 kg/m$^3$.

Silicone putty is commonly used to model salt, but it has also been used to model overpressured shales (e.g. Cohen and McClay, 1996; Wu and McClay, 2011). To take into account overpressures and pore fluids in decollement levels such as shales, physical modelling techniques have been developed using compressed air injected into beeswax microspheres (e.g. Cobbold and Castro, 1999; Cobbold et al., 2001; Mourgues and Cobbold, 2003; Zanella et al., 2014). The implementation of these techniques is complicated and remains impractical for experiments with three decollement levels, explaining why such an approach is not adopted here.

The experimental apparatus consists of a fixed wall screwed to a rigid and fixed basal plate, over which another wall fixed to a thin mobile basal plate is pushed at a constant rate (Fig. 1a). The two other sides are free and supported by sand to ensure uniform stresses. The displacement of the basal mobile plate induces a velocity discontinuity (VD) at its border, which localizes the deformation at the base of the model. (cf. Malavieille, 1984; Balé, 1986; Ballard, 1989). In our experiments, we use a VD to simulate only one structure, with the VD representing the zone localizing the deformation at the base of the model. The VD may represent either a basement fault, (e.g. Richard et al., 1991) or, in an imbricate thrust system, the tip line of a basal decollement (Boyer and Elliot, 1982; Casas et al., 2001). The experiment is set up in a 100 x 60 cm sandbox, wide enough to allow the model to be cut into several vertical slices after each phase of deformation without border effects (see below).

To facilitate comparisons with natural examples such as the Bolivian Subandean fold and thrust belt, where several decollement levels are present, we set up experiments composed of a four-layer brittle-ductile system. The prekinematic pile consists of layers including, from bottom to top: 1 cm of purple silicone (lower decollement level); 1.2 cm of black and white sand; 0.8 cm of transparent silicone (middle decollement level); and 3 cm of black and white sand. The layer of black and white
sand is composed of two 1.5 cm layers separated by a thin layer (0.3 cm) of silicone to facilitate flexural slip (Fig. 1a). The synkinematic pile is composed of blue and white sand layers of different thicknesses. To simulate synkinematic mass transfer, both sedimentation and erosion are simulated. Sedimentation is simulated using fresh sand (blue and white) that is continuously sprinkled manually onto the model during the shortening (e.g. Cobbold et al., 1993; Baby et al., 1995; Storti and McClay, 1995; Barrier et al., 2002). Erosion is simulated by removing sand with a vacuum cleaner. To define the amount of sedimentation, we use the dimensionless parameter \( R = \frac{V_s}{V_u} \), where \( R \) is the ratio between the rate of the sedimentation \( V_s \) and the velocity of uplift of the structure \( V_u \) (see Barrier et al., 2002; Pichot and Nalpas, 2009). To define the amount of erosion, we use a dimensionless parameter \( E = \frac{V_e}{V_u} \), where \( E \) is the ratio between the velocity of the erosion \( V_e \) and the velocity of uplift of the structure \( V_u \). The switchover between erosion and sedimentation corresponds to a base level in the stratigraphic sense (Posamentier et al., 1988; Posamentier and Vail, 1988), which implies that the system is being eroded above the base level, with transit occurring along this level and sedimentation below. Different sedimentation modes are chosen to represent the range of possible sedimentation rates within natural basins (Fig. 1b). In the first series of experiments, models are performed without sedimentation \( (R = 0) \), the second series with sedimentation and erosion \( (R = 1/2 \text{ and } E = 1/4) \), the third series with sedimentation alone \( (R = 1) \) and the fourth series with a high sedimentation/uplift ratio \( (R = 2) \). The variations of mass transfer between our experiments are comparable to different geographic positions in the Bolivian Subandean fold and thrust belt, ranging from the western zone with erosion, through the central foredeep with a high sedimentation rate to the eastern zone with a low sedimentation rate.

Table 1 presents the geometric and dynamic scaling of the models. The scale ratios for dimensions and stress between the models and nature are of the same order of magnitude \( (10^{-5}) \), and the shortening rate is imposed by the scaling laws. A velocity of 1 cm/h is used for displacement of the piston, mobile basal plate and wall, along with the associated velocity discontinuity (VD). Photographs of the model surface are taken at regular time intervals (every 15 min) to observe the development of the structure. Sand layers are made up of various colours; black and white for the prekinematic layers, and blue and white for the synkinematic layers (the colour of the sand does not modify its behaviour). After deformation, the internal structures and their time-evolution are observed in a series of cross-sections cut parallel to the compression direction and perpendicular to the VD. The experiments are conducted in three steps of shortening: i) compression of 5 cm; ii) compression of 7.5 cm; and iii) compression of 10 cm. All the cross-sections extracted after each
step are taken at a distance of at least 5 cm from the lateral border of the model, in order to avoid
boundary effects. The deformation is not affected by stopping between steps. This is verified by an
experiment in which 10 cm of shortening in one step yields the same amount of deformation as the
experiment performed in 3 shortening steps. Although a total of twenty experiments were
performed to test the reproducibility (denoted Bode 1 to Bode 20), only the results of four
experiments are presented here.

To simplify the description of the silicone/sand pile of the model, we use the following terminology
(Fig. 2). From bottom to top, the prekinematic layers are called: lower silicone layer; lower sand
layer; middle silicone layer; middle sand layer; upper silicone layer; upper sand layer. The layers
added during the experiment are termed synkinematic sand layers. The thrusts are named according
to the sand layers affected and their geometry in relation to the VD inducing shear displacement
(Ballard, 1989). For example, a synthetic thrust occurs when the hanging wall moves in a direction
opposite to the movement of the mobile plate, and an antithetic thrust is characterized by the
hanging wall moving in the same direction as the mobile plate. Therefore, as shown in Figure 2, the
thrusts are referred to as follows, from bottom to top: lower synthetic thrust; middle antithetic
thrust; upper synthetic thrust. The faults are colour coded to highlight the movement of the faults
for each step of deformation (Fig. 3). The forward or backward propagation of the deformation is
defined with respect to the previous structure considered (Fig. 2).

3. Results of analogue modelling experiments

3.1. Shortening without sedimentation, R = 0 (Fig. 3a)

The main feature observed in this experiment is the synthetic vergence of all thrusts, associated with
a forward propagation of the deformation.

More precisely:

- After 5 cm of shortening (Fig. 3a1), the lower and middle sand layers are affected by synthetic
thrusts generating penetration of the lower and middle sand layers into the middle and upper
silicone layers, respectively. The upper sand layer is affected by a synthetic thrust with a very
shallow dip.
- After 7.5 cm of shortening (Fig. 3a2), the anticline in the lower sand layer is amplified and associated with an accumulation of silicone forming a ridge in the lower silicone layer near the VD. The lower and middle synthetic thrusts grow in amplitude and are rotated anticlockwise. The upper synthetic thrust is still active, and a pop-up structure develops in front of the thrust (in yellow in Fig. 3a2).

- After 10 cm of shortening (Fig. 3a3), the lower and middle synthetic thrusts have undergone anticlockwise rotation and become no longer active. In addition, a new lower synthetic thrust develops (in yellow in Fig. 3a3). The upper synthetic thrust and the associated pop-up structure are still active. The layers are affected by an amplification of the folding.

3.2. Shortening with synkinematic sedimentation and erosion, $R = 1/2, E = 1/4$ (Fig. 3b)

The main feature of this experiment is the change in vergence of the middle and upper antithetic thrusts after 10 cm of shortening.

More precisely:

- After 5 cm of shortening (Fig. 3b1), the lower sand layer is affected by a synthetic thrust of flat geometry that penetrates the middle silicone layer. The middle and upper sand layers are affected by an antithetic thrust. Firstly, the middle antithetic thrust penetrates slightly into the upper silicone layer, and then, while showing a steeper dip, it connects up with the upper antithetic thrust. The upper sand layer is slightly eroded on the crest of the ramp anticline. The synkinematic layers show onlap geometry on the hanging wall of the upper thrust, and toplap geometry below the base of the thrust in the footwall.

- After 7.5 cm of shortening (Fig. 3b2), the deformation is similar to that observed for 5 cm of shortening with the same synthetic and antithetic thrusts. The lower synthetic thrust shows a large penetration into the middle silicone layer. An amplification of the middle and upper antithetic thrusts induces more uplift and erosion on the crest of the ramp anticline in the upper sand layer. The synkinematic layers show the same overall geometry with increasing deformation.

- After 10 cm of shortening (Fig. 3b3), a change in the vergence of the deformation is observed. The lower synthetic thrust penetrates deeply into the middle silicone layer, while an incipient lower antithetic thrust is developed (in yellow in Fig. 3b3). The lower synthetic thrust is deformed, in
relation to a thickening of the lower silicone layer near the VD. New middle and upper synthetic
thrusts cut the previous middle and upper antithetic thrusts. The previous middle and upper
antithetic thrusts are slightly rotated clockwise and displaced passively on the hanging wall of the
newly formed middle and upper synthetic thrusts. The synkinematic layers deposited during the
growth of these synthetic thrusts show onlap geometry on their hanging wall, thus sealing the
previous antithetic thrust. These layers also show toplap geometry below the base of the synthetic
thrust in the footwall.

3.3. Shortening with synkinematic sedimentation, $R = 1$ (Fig. 3c)

The main feature of this experiment is that all the sand layers are affected by thrusts of opposite
vergence developing a typical fish-tail structure.

More precisely:

- After 5 cm of shortening (Fig. 3c1), the lower sand layer is affected by a lower synthetic thrust
  that penetrates the middle silicone layer. The middle sand layer is affected by a middle antithetic
  thrust that penetrates into the upper silicone layer. The upper sand layer is affected by an upper
  synthetic steeply dipping thrust with an incipient upper antithetic fault in its hanging wall. This
  faulting pattern with opposing vergence is typical of a fish-tail structure. The synkinematic layers
  show onlap geometry on the hanging wall of the upper thrust, and toplap geometry below the base
  of the thrust in the footwall.

- After 7.5 cm of shortening (Fig. 3c2), the lower antithetic thrust penetrates deeply into the middle
  silicone layer. The middle antithetic thrust has ceased growing and a new steeply dipping antithetic
  thrust is formed cutting the upper sand layer and affecting the synkinematic layers. The upper
  synthetic thrust ceases and a new upper antithetic thrust cuts the previous synthetic thrust and
  synkinematic layers. The synkinematic layers show onlap geometry in the direction of the anticline
  crest.

- After 10 cm of shortening (Fig. 3c3), the lower synthetic thrust penetrates deeply into the middle
  silicone layer without anticline growth. The growth of the middle antithetic thrust continues until it
  is cut by a new synthetic thrust. This thrust has variable dip, the lower part being nearly horizontal,
  and the upper part steeply dipping (in yellow in Fig. 3c3). The vertical amplification of the
structures in the centre of the model is associated with a verticalization of the prekinematic layers. The synkinematic layers show onlap geometry in the direction of the anticline crest.

3.4. Shortening with synkinematic sedimentation, $R = 2$ (Fig. 3d)

The main feature of this experiment is that all sand layers are affected by thrusts with opposing vergence, thus developing a typical fish-tail structure. Finally, at the end of the shortening, the deformation shows a double vergence.

More precisely:

- After 5 cm of shortening (Fig. 3d1), the lower sand layer is affected by a lower synthetic thrust that penetrates into the middle silicone layer. The middle sand layer is affected by a middle antithetic thrust that penetrates into the upper silicone layer. The upper sand layer is affected by a major upper synthetic thrust and an incipient antithetic thrust. Although such a fault pattern with opposing vergence is typical of a fish-tail structure, there is less folding and uplift in this case than previously observed (Fig. 3c1). The synkinematic layers show a progressive decrease in the thickness of the hanging wall in the direction of the upper synthetic thrust (in green in Fig. 3d1), and a nearly constant thickness on its footwall. The thrusts near the piston in the middle and upper sand layers are due to boundary effects at the beginning of the experiment (in grey in Fig. 3d).

- After 7.5 cm of shortening (Fig. 3d2), the deformation is similar to that observed for 5 cm of shortening. The lower synthetic thrust shows deep penetration into the middle silicone layer. The growth of the middle antithetic thrust continues and an incipient middle antithetic fault is formed. The upper synthetic and antithetic thrusts are still active, associated with the development of a new incipient antithetic thrust. The synkinematic layers show the same overall geometry as before.

- After 10 cm of shortening (Fig. 3d3), the lower synthetic thrust penetrates deeply into the middle silicone layer, and the lower sand layer is also affected by a new antithetic thrust. The middle antithetic thrust is cut by a middle synthetic thrust. The upper sand layer and the synkinematic layers are affected by a synthetic and an antithetic thrust, as well as a new synthetic thrust. These associated faults induce a double vergence in the deformation, and the synkinematic layers display a relatively constant thickness.

3.5. Time-evolution of structure uplift (Fig. 4)
The time-evolution of the anticline crest uplift, which is associated with the thrusts, affects the lower and upper sand layers in completely different ways depending on the R ratio. The maximum uplift of the upper sand layer anticline is observed when the sedimentation rate is equal to the uplift velocity (R = 1), and the minimum uplift is observed when there is no sedimentation (R = 0). On the contrary, the maximum uplift of the lower sand layer structure is observed when there is no sedimentation (R = 0) and minimum uplift occurs when the sedimentation rate is equal to or greater than the velocity of uplift (R = 2 or 1). It is important to note that the amplitude of the uplift is nearly the same (around 4 cm) for the lower and upper sand structure when there is no sedimentation (R = 0). When the sedimentation rate is equal to the uplift velocity (R = 1), the amplitude of the uplift in the upper sand layer is three times that of the lower sand layer (around 7.5 cm and 2.5 cm, respectively). Note that, when the sedimentation/uplift ratio is intermediate between these two cases (R = 1/2, E = 1/4), the amplitude of the uplift is also intermediate. When the sedimentation rate is double the uplift velocity (R = 2), the uplift of the lower sand layer structure decreases to its minimum amplitude, while the uplift of the upper sand layer structure is lower than for R = 1 and R = 1/2, with E = 1/4, as noted by Barrier et al. (2013).

4. Discussion

4.1. Influence of initial mechanical stratigraphy

The initial mechanical stratigraphy is characterized by the presence of interbedded silicone layers and sand layers that allow decoupling between the sand layers. Firstly, a typical flat lower thrust is developed because the lower sand layers penetrate into the middle detachment level (see Fig. 5 for main features of experiments after 10 cm of shortening). The geometry of the upper reverse fault is dependent on the sedimentation/uplift ratio (e.g. Pichot and Nalpas, 2009; Barrier et al., 2013), and shows a maximum dip when R = 1 or 2 (Fig. 3a1, b1, c1, d1 and 5, see \( \alpha < \beta \)). Secondly, two superposed thrusts with opposite vergence create a fish-tail structure when the interbedded silicone layer acts as a decollement level (Figs. 3c1 and d1). These fish-tail structures are created only when sedimentation occurs during deformation (for R = 1 and 2). In the experiment with low ratios of sedimentation and erosion with respect to uplift of the structure (R = 1/2, E = 1/4), a fish-tail structure is only present between the lower and middle sand layers (Fig. 3b). In the experiment without sedimentation, no fish-tail structures are created (Fig. 3a). Therefore, the presence of decollement levels is a necessary but insufficient condition to
produce such fish-tail structures. Thirdly, the presence of a decollement level allows the
deformation to propagate forward of the main upper structure (Figs. 3a2 and a3), provided there is
no sedimentation. Finally, we suggest it is necessary to have an initial mechanical stratigraphy with
several decollement levels to create specific features such as fish-tail structures and forward
propagation of the deformation. However, the presence of several decollement levels is insufficient
to explain the geometric evolution and variability of the structures.

4.2. Influence of shortening

Increasing shortening induces major deformation in the model, creating structures with a marked
uplift (Fig. 4), and an increase in the thrust throw. Firstly, during the increase in the amount of
shortening, two possible trends of development can be observed. When there is no sedimentation,
the model develops an overall asymmetric shape (Figs. 3a1 to a3). Alternatively, in the experiment
with sedimentation, the shape of the model evolves from asymmetric to doubly vergent (Figs. 3b3,
c1 to c3, and d1 to d3). Secondly, increased shortening enhances the penetration of thrusts into the
overlying silicone layer. Thirdly, although increased shortening allows the deformation to propagate
forward (Figs. 3a2 and a3), this can only take place in the absence of sedimentation. Finally, we
suggest that increased shortening is necessary to ensure an evolution in the overall shape of the
model, but is not sufficient to explain why this evolution is possible.

4.3. Influence of synkinematic sedimentation

The geometry of the structure is highly dependent on the sedimentation/uplift ratio (Figs. 3 and 5).
Without sedimentation, the geometry of structures is similar in the lower, middle and upper layers
insofar as they display the same synthetic vergence. Any increase in the shortening is
accommodated by a forward propagation of the deformation (Figs. 3a and 5a). By contrast, with
sedimentation, the geometry of the structures is different in the lower, middle and upper layers with
different vergence. Also there is no propagation of the deformation during shortening, and all the
structures are stacked above the VD (Figs. 3b, c, d and 5b, c).

With sedimentation, the geometry of the faults shows a fish-tail structure for the lower and middle
sand layers when R = 1/2 with ongoing erosion (E = 1/4), and for all layers when R = 1 and 2 (Figs.
3 and 5). This implies that more fish-tail structures are developed when the sedimentation rate is
higher. Such an effect may be related to an increase in normal stress induced by the synkinematic
layers, which increases the strength of the interbedded sand layers. In this way, the differential strength between the sand and silicone layers increases, thereby making it easier for the sand layers to penetrate the silicone layers.

During deformation, the overall shape of the model changes from asymmetric to doubly vergent, with an increase in shortening that is only observed with synkinematic sedimentation. With an increase in sedimentation with respect to uplift (R = 1 to 2), the model shows an increasingly prominent doubly vergent shape.

In agreement with previous experimental studies (e.g. Tondji-Biyo, 1995; Nalpas et al., 1999; Barrier et al., 2002; Nalpas et al., 2003; Pichot and Nalpas, 2009; Barrier et al., 2013), synkinematic sedimentation strongly influences the uplift of compressive growth structures. When R = 0, the effect of shortening in the lower and upper layers is the same, being associated with forward propagation of the deformation without major uplift. The maximum uplift is found in the experiment with R = 1 (Figs. 3, 4 and 5), but it is noteworthy that, when the uplift of the upper structure increases, the lower structure undergoes less uplift (Fig. 4). When R = 1, the effect of shortening in the lower and upper layers is different: the lower layer propagates horizontally, while the upper layer grows vertically. The uplift of the lower structure is inhibited by the weight of the sediments, which explains why there is minor uplift for R = 2, and major uplift for R = 0.

5. Comparison with natural examples

The structural style of the Bolivian Subandean foothills is characterized by elongated N-S trending tight folds in the Chaco Basin (Figs. 6a and b). The geometry of the fold and thrust belt is mainly controlled by lithology and the presence of three main potential decollement levels (Baby et al, 1989; Baby et al, 1992; Moretti et al., 1996; Giraud and Limachi, 2001; Moretti et al., 2002). The basal decollement level is located in the Kirusillas shales (Late Silurian). The middle decollement levels are identified at Icla (Early Devonian) and Los Monos (Late Devonian), where potential decollement is controlled by the clay content of the formations involved. The decollement levels partly disconnect the deformation observed at the surface (Tertiary to Lower Carboniferous series) from that occurring at depth (Devonian sandstones, Huamampampa, Fig. 6c). The upper decollement level, which is the thinnest, is located in the Ipaguazu Formation, which is composed of gypsum and shales (Triassic). Fluid overpressure in maturing source rocks may have an effect on detachments and the propagation of deformation in compressive systems (Cobbold and Rodrigues,
2007; Cobbold et al., 2009), but we do not discuss this possibility here because we have only
analysed the geometry of isolated structures.

The Chaco Basin is a classical foreland basin in a retro arc position (Uba et al., 2005 and 2006).
Tertiary sedimentation is regarded as taking place in a foreland basin sequence during the Late
Oligocene to Early Miocene. The base of this sequence is represented by the unconformable fluvial
Petaca Formation (Late Oligocene to Early Miocene), which may be attributed to sedimentation in a
forebulge-backbulge depocentre. The overlying Yecua Formation (Middle to Late Miocene)
corresponds to the onset of active deformation and large-scale subsidence in response to thrust-belt
loading on a regional scale (distal foredeep). The overlying Tariquia Formation (Late Miocene) is
concomitant with the onset of deposition of Andean derived sediment in the medial-foredeep
depocentre. In our study area, eastward from the Incahuasi structure (Fig. 6b), these formations may
be considered as of relatively constant thickness and are thus pre-tectonic. In the western part of our
study area, westward from the Incahuasi structure (Fig. 6b), these formations are of variable
thickness and may be considered as syn-tectonic.

The Guandacay Formation (Late Miocene to Early Pliocene) and Emborozu Formation (Late
Pliocene to Pleistocene) are coeval with the propagation of the deformation front in the Subandean
Zone and thus represent true syntectonic deposits associated with the emplacement of the folds and
thrusts in our studied area (Incahuasi structure). Their thickness can vary between 1000 - 3500 m.
The age of the Guandacay Formation corresponds to the peak of shortening calculated by Moretti et
al. (1996).

As hydrocarbon exploration in Bolivia targets a deep-seated reservoir below the main upper
decollement (Devonian Los Monos Formation), some of these N-S trending tight folds have been
drilled and some seismic data exists. The quality of seismic data in the Subandean Zone is poor and
this hinders clear imaging of the deep-seated structures. Therefore, it is difficult to interpret the
seismic data, which often give rise to misleading interpretations. Among the folds in the area, the
Incahuasi anticline shows some interesting features. Three exploration wells drilled on the anticline
axis confirm that the top of the Huamampampa Formation is offset by at least 1 km to the east with
respect to the surface anticline axial plane (Fig. 7) as evidenced by sampling and dipmeter data
acquired during drilling. The surface Incahuasi structure is overturned towards the west and shows a
vergence contrary to that of most other folds in the Subandean Zone (Fig. 6). The main backthrust
that accommodates this overfolding is rooted in the basal shale of the Los Monos Formation, close
to the interface with the Huamampampa quartzites. The dipmeter data in wells confirm the fact that
the deep-seated thrust system affecting the Huamampampa Formation also faces towards the west
(hinterland). Geological cross-sections constrained by field and several wells data confirm that the
Incahuasi thrust, facing towards the east, has been passively rotated by the emplacement of the
backthrust (Figs. 6 and 7), which postdates the Incahuasi thrust, in the same way as reproduced by
analogue modelling (Figs. 3b).

A comparison between the Incahuasi subsurface data and the analogue experiments (inverted cross-
section of the model of figure 3b3) allows us to propose an interpretation of the Incahuasi structure
in a cross-section showing the evolution of the thrust in time and space (Fig. 7). The overall
evolution corresponds to an inversion of the vergence of the thrust. The first fault propagation fold
is cut and displaced passively along with the hanging wall of the newly formed thrust fault.
Therefore, the change in the vergence of the Incahuasi fold may be explained by the influence of
sedimentation rate. Figure 7 compares the subsurface data, their interpretation and the interpreted
cross-section of a model, showing the positive contribution of analogue modelling to an improved
interpretation of the seismic lines.

A comparison can also be made between the experimental results and subsurface data for the whole
cross-section of the Subandean system (Fig. 6b). We propose that, in the eastern part, the structures
of Camiri, Carohuaycho Los Huesos, Caipipendi and Charagua are characterized by major
asymmetric geometries and propagation of deformation in front of the thrust, which is characteristic
of the experiment with low sedimentation rate (Figs. 3a and 5a). The central zone corresponding to
the Incahuasi structure shows a drastic change in vergence direction, which is comparable to the
experiment with a medium rate of sedimentation (Figs. 3b and 5b). The western structures of
Ilinchunpa and Inau are characterized by a double vergence and vertical propagation of the
deforation, corresponding to the experiment with high sedimentation rate (Figs. 3c3, d3; and 5c).
Thus, this lateral variation in the structures (see also Baby et al., 1992; Moretti et al., 1996; Giraudo
and Limachi, 2001; Moretti et al., 2002) is consistent with an increase in shortening from east to
west and a decrease in rate of sedimentation from the hinterland toward the foreland.

6. Conclusions

The experimental results presented here suggest that:
a - The initial mechanical stratigraphy and the presence of several decollement levels are necessary conditions for the creation of specific features related to decoupling between sand layers, such as fish-tail structures and the propagation of deformation. However, these conditions alone cannot explain the evolution and variability in the geometries of the structures.

b - The final geometry of the structure seems to be highly dependent on the sedimentation/uplift ratio, $R$. When $R = 0$ (no sedimentation), the deformation propagates forward with an overall asymmetric shape. When $R = 1/2$ or 1 (low sedimentation rate), the deformation increases vertically with steeply dipping faults, and the vergence of the structure changes with the development of a thrust with opposite vergence. When $R = 2$ (high sedimentation rate), the deformation creates a pattern of doubly vergent structures at the surface and at depth, with the development of a conjugate structure and associated uplift.

c - The expression of deformation in the brittle layers below the upper decollement levels is different compared with layers above the upper decollement levels, and depends on decoupling and sedimentation rate. With low mass transfer (low sedimentation rate), the lower and upper brittle layers are deformed in the same way with the same amount of uplift. On the other hand, with high mass transfer (high sedimentation rate), the lower brittle layers show much less uplift than the upper brittle layers.

d - Application of the analogue modelling results to the Subandean compressive system suggests that the west to east evolution of the structures in the thrust and fold belt (from doubly vergent with several faults and large uplift to asymmetric with a single major fault) is related to the variation in the amount of shortening and sedimentation rate.

e - Seismic lines have low resolution in compressive systems with intense deformation and steeply dipping layers. Therefore, in such a context, analogue modelling can be a useful tool for exploring the geometric possibilities in relation to the evolution of structures, allowing us to improve the interpretation of seismic lines.

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Figure and Table captions

Figure 1: (a) Experimental apparatus and (b) sketch of the homogeneous and local synkinematic sedimentation. R is the ratio between the sedimentation rate, Vs, and the velocity of structure uplift, Vu (R = Vs/Vu, see Barrier et al., 2002). E is the ratio between the erosion rate, Ve, and the velocity of structure uplift, Vu (E = Ve/Vu).

Figure 2: Cross-section showing the terminology used in the description of the experiments.

Figure 3: Cross-sections of experiments for 5, 7.5, 10 cm of shortening. a1 to a3: for R = 0; b1 to b3: for R = 1/2 and E = 1/4; c1 to c3: for R = 1; d1 to d3: for R = 2. The colour coding used is green for a fault active only at the beginning of deformation, red for a fault active throughout deformation and yellow for a fault active at the end of deformation. "Bode" and "Repa" denote different experiments.
Figure 4: Diagram showing time-evolution of uplift of the upper and lower structures during compression.

Figure 5: Schematic cross-section of experiments after 10 cm of shortening showing the main features of the structures.

Figure 6: (a) Geological map of Bolivia showing location of the interpreted seismic line (YPFB-SERGEOMIN, 1996), (b) Cross-section of the Subandean fold and thrust belts across the Incahuasi structure (using surface and subsurface data), the names correspond to the main structures. (c) Stratigraphic column of the Bolivian Subandean Zone (Moretti et al., 2002), interpreted in terms of mechanical stratigraphy, compared with structures obtained in the analogue experiments.

Figure 7: (a) Subsurface data (seismic line and well) for the Incahuasi structure. (b) Interpretation of the Incahuasi structure (c) Inverted cross-section of experiment b after 10 cm of shortening (see figure 3b3).

Table 1: Scaling of parameters between nature and models. L, g, ρ, μ, V, t, and σ represent the length, acceleration due to gravity, density, viscosity, shortening rate, time and stress, respectively.
<table>
<thead>
<tr>
<th></th>
<th>( L )</th>
<th>( g )</th>
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<th>( \mu )</th>
<th>( V )</th>
<th>( t )</th>
<th>( \sigma )</th>
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<tr>
<td></td>
<td>(m)</td>
<td>(m/s(^2))</td>
<td>(kg/m(^3))</td>
<td>(Pa·s)</td>
<td>(m/s)</td>
<td>(s)</td>
<td>(Pa)</td>
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<tr>
<td><strong>Nature</strong></td>
<td>1000</td>
<td>9.81</td>
<td>2300</td>
<td>2x10(^{17})</td>
<td>3.2x10(^{10})</td>
<td>3.1x10(^{17})</td>
<td>2.2x10(^{7})</td>
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<td></td>
<td>(1 km)</td>
<td></td>
<td></td>
<td></td>
<td>(±1cm/year)</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Model</strong></td>
<td>0.01</td>
<td>9.81</td>
<td>1400</td>
<td>1.4x10(^{17})</td>
<td>2.7x10(^{-6})</td>
<td>3.6x10(^{8})</td>
<td>1.3x10(^{2})</td>
</tr>
<tr>
<td></td>
<td>(1 cm)</td>
<td></td>
<td></td>
<td></td>
<td>(1 cm/h)</td>
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<td></td>
</tr>
<tr>
<td><strong>Model/nature ratio</strong></td>
<td>10(^{-5})</td>
<td>1</td>
<td>0.6</td>
<td>7x10(^{-15})</td>
<td>8.7x10(^{-9})</td>
<td>1.1x10(^{-9})</td>
<td>6.1x10(^{6})</td>
</tr>
</tbody>
</table>
Figure a shows a cross-sectional diagram with labeled layers:
- Mobile wall
- Fixed wall
- Compression
- 1.5 cm sand
- 0.3 cm silicone
- 1.5 cm sand
- 0.8 cm silicone
- 1.2 cm sand
- 1 cm silicone

Below the layers, the term "basal mobile plate" and "basal fixed plate" are indicated.

Figure b illustrates various scenarios with labels:
- $R = 0$ (Exp a)
- $R = 1/2 E = 1/4$ (Exp b)
- $R = 1$ (Exp c)
- $R = 2$ (Exp d)

Scenarios include:
- Erosion
- Base level sedimentation

The diagram includes a Velocity Discontinuity (VD) notation.
a - Subsurface data

b - Interpretation of Incahuausi structure

c - Cross-section of experiment

permanent active fault  early fault  late fault
HIGHLIGHTS

- With décollement levels, models of compressive system show fish-tail structure
- Synkinematic sedimentation favour vertical uplift and double vergence in thrust structure
- Models allow to better interpret seismic lines in compressive systems
- The evolution of Subandean structures is related to shortening and mass transfer